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# Uniform Hlder regularity with small exponent in competition-fractional diffusion systems 

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# UNIFORM HÖLDER REGULARITY WITH SMALL EXPONENT IN COMPETITION-FRACTIONAL DIFFUSION SYSTEMS. 

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$$
\begin{aligned}
& \text { AbStract. For a class of competition-diffusion nonlinear systems involving } \\
& \text { the } s \text {-power of the Laplacian, } s \in(0,1) \text {, of the form } \\
& \qquad(-\Delta)^{s} u_{i}=f_{i}\left(u_{i}\right)-\beta u_{i} \sum_{j \neq i} a_{i j} u_{j}^{2}, \quad i=1, \ldots, k, \\
& \text { we prove that } L^{\infty} \text { boundedness implies } \mathcal{C}^{0, \alpha} \text { boundedness for } \alpha>0 \text { sufficiently } \\
& \text { small, uniformly as } \beta \rightarrow+\infty \text {. This extends to the case } s \neq 1 / 2 \text { part of the } \\
& \text { results obtained by the authors in the previous paper [arXiv:1211.6087v1]. }
\end{aligned}
$$

## 1. Introduction

In this paper we study the problem

$$
\left\{\begin{array}{l}
(-\Delta)^{s} u_{i}=f_{i, \beta}\left(u_{i}\right)-\beta u_{i} \sum_{j \neq i} a_{i j} u_{j}^{2}  \tag{1.1}\\
u_{i} \in H^{s}\left(\mathbb{R}^{N}\right),
\end{array}\right.
$$

in dimension $N \geq 2$, where $a_{i j}=a_{j i}>0, \beta$ is positive and large, and the non-local operator

$$
(-\Delta)^{s} u(x)=c_{N, s} \operatorname{pv} \int_{\mathbb{R}^{N}} \frac{u(x)-u(\xi)}{|x-\xi|^{N+2 s}} \mathrm{~d} \xi
$$

denotes the $s$-power of the laplacian. We are mostly concerned with the asymptotic behavior of the solutions to the previous system as the parameter $\beta \rightarrow+\infty$ : as we shall see, this entails spatial segregation for the limiting profiles. Our aim is to prove uniform in $\beta$ bounds in Hölder spaces, extending to the case $s \in(0,1)$ part of the results that we already obtained for the case $s=1 / 2$ in the recent paper [19], to which we refer for further details.

Segregation-diffusion problems arise in different applicative contests, from biological models for competing species to the phase-segregation phenomenon in BoseEinstein condensation. Regarding the standard diffusion case $(s=1)$, a broad literature is present. Among the others, we mention the papers $[7,8,3,2,21,1$, $20,9,18,10,11]$, which are mostly concerned with regularity issues. Our study is motivated by the recent interest that has developed around equations involving fractional laplacians, as they model long-jump diffusion processes in population dynamics, and they naturally appear in relativistic corrections of quantum field theory.

[^0]Exploiting the local realization of the fractional laplacian $(-\Delta)^{s}$ as a Dirichlet-to-Neumann map (see, for instance, [6]), semilinear problems involving fractional laplacians have been the object of a massive study. Accordingly, letting $a:=1-2 s \in$ $(-1,1)$, if we introduce the differential operator (on the ( $N+1$ )-dimensional space)

$$
L_{a} v:=-\operatorname{div}\left(\left.|y|\right|^{a} \nabla v\right),
$$

and define

$$
\partial_{\nu}^{a} v:=\lim _{y \rightarrow 0^{+}}-y^{a} \partial_{y} v
$$

we obtain that, up to normalization constants, the problem
$(P)_{\beta}^{s}$

$$
\begin{cases}L_{a} v_{i}=0 & \text { in } B_{1}^{+} \\ \partial_{\nu}^{a} v_{i}=f_{i, \beta}\left(v_{i}\right)-\beta v_{i} \sum_{j \neq i} a_{i j} v_{j}^{2} & \\ \text { on } \partial^{0} B_{1}^{+}\end{cases}
$$

is a localized version of (1.1), with $u_{i}(x)=v_{i}(x, 0)$. Here, as usual, we write $\mathbb{R}_{+}^{N+1} \ni X=(x, y)$ and $B_{r}^{+}\left(x_{0}, 0\right):=B_{r}\left(x_{0}, 0\right) \cap\{y>0\}$, which boundary contains the spherical part $\partial^{+} B_{r}^{+}:=\partial B_{r} \cap\{y>0\}$ and the flat one $\partial^{0} B_{r}^{+}:=B_{r} \cap\{y=0\}$. Well known properties of the Muckenhoupt $A_{2}$-weights (see for instance [15]) allow to provide a weak formulation of $(P)_{\beta}^{s}$ in the weighted space

$$
H^{1 ; a}(\Omega):=\left\{v: \int_{\Omega} y^{a}\left(|v|^{2}+|\nabla v|^{2}\right) \mathrm{d} x \mathrm{~d} y<\infty\right\}
$$

endowed with its natural Hilbert structure.
The main result we prove in this paper is the following.
Theorem 1.1 (Local uniform Hölder bounds). Let the functions $f_{i, \beta}$ be continuous and uniformly bounded (w.r.t. $\beta$ ) on bounded sets. There exists $\alpha=\alpha(N, s)>0$ such that, for every $\left\{\mathbf{v}_{\beta}\right\}_{\beta}$ family of $H^{1 ; a}\left(B_{1}^{+}\right)$solutions to the problems $(P)_{\beta}^{s}$,

$$
\left\|\mathbf{v}_{\beta}\right\|_{L^{\infty}\left(B_{1}^{+}\right)} \leq M \quad \Longrightarrow \quad\left\|\mathbf{v}_{\beta}\right\|_{\mathcal{C}^{0, \alpha}}\left(\overline{B_{1 / 2}^{+}}\right) \leq C
$$

where $C=C(M, \alpha)$. Furthermore, $\left\{\mathbf{v}_{\beta}\right\}_{\beta>0}$ is relatively compact in $H^{1 ; a}\left(B_{1 / 2}^{+}\right) \cap$ $\mathcal{C}^{0, \alpha}\left(\overline{B_{1 / 2}^{+}}\right)$.

The above result allows to prove its natural global counterpart, either on the whole of $\mathbb{R}^{N}$ or on domains with suitable boundary conditions.
Theorem 1.2 (Global uniform Hölder bounds). Let $f_{i, \beta}$ and $\alpha$ be as in the previous theorem, and let $\left\{\mathbf{u}_{\beta}\right\}_{\beta}$ be a family of $H^{s}\left(\mathbb{R}^{N}\right)$ solutions to the problems

$$
\begin{cases}(-\Delta)^{s} u_{i}=f_{i, \beta}\left(u_{i}\right)-\beta u_{i} \sum_{j \neq i} a_{i j} u_{j}^{2} & \text { in } \Omega \\ u_{i} \equiv 0 & \text { in } \mathbb{R}^{N} \backslash \Omega\end{cases}
$$

where $\Omega$ is a bounded domain of $\mathbb{R}^{N}$, with smooth boundary. Then

$$
\left\|\mathbf{u}_{\beta}\right\|_{L^{\infty}(\Omega)} \leq M \quad \Longrightarrow \quad\left\|\mathbf{u}_{\beta}\right\|_{\mathcal{C}^{0, \alpha}\left(\mathbb{R}^{N}\right)} \leq C(M, \alpha)
$$

Of course, a natural question regards the optimal regularity of such problems, that is the maximal value of $\alpha$ for the above results to hold. In the case of the standard diffusion $(s=1)$, the analogous issue is faced in [14], where uniform Hölder bounds are shown for every $\alpha<1$. The proof of this result relies on a blowup procedure, leading to a contradiction with some Liouville type theorems; these are based on the validity of some monotonicity formulae of Alt-Caffarelli-Friedman
and Almgren type. In [19], we consider the case $s=1 / 2$. In the situation there, a two-step strategy has been developed: indeed, though providing some uniform Hölder bounds, the above blow-up procedure seems not enough to catch the optimal regularity threshold. The main reason for this failure is the lack of an exact Alt-Caffarelli-Friedman formula, so that the bounds, at a first stage, are obtained only when $\alpha$ is smaller than some number $\nu^{\mathrm{ACF}}>0$, which is not explicit. Nonetheless, this provides enough compactness to trigger the second step of the strategy, based on the classification of the possible profiles obtained through a blow-down argument. At the end of the procedure, uniform bounds for any $\alpha<1 / 2$ are shown. In this perspective, Theorem 1.1 here corresponds to the first step (the blow-up procedure) of the strategy just described, extended to the general case $s \in(0,1)$. The exponent $\alpha$ mentioned there is subject to two main restrictions: as before, $\alpha$ is bounded above by the minimal rate of growth for multi-phase segregation profiles $\nu^{\mathrm{ACF}}$; on the other hand, when $s>1 / 2$, a new upper threshold must be taken into account, which is related to the phenomenon of self-segregation.

The first restriction, as we mentioned, is related to the validity of an exact Alt-Caffarelli-Friedmann formula, which in turn depends on an optimal partition problem. More precisely, let $\mathbb{S}_{+}^{N}:=\partial^{+} B^{+}$. For each open $\omega \subset \mathbb{S}^{N-1}:=\partial \mathbb{S}_{+}^{N}$ we define the first $s$-eigenvalue associated to $\omega$ as

$$
\begin{equation*}
\lambda_{1}^{s}(\omega):=\inf \left\{\frac{\int_{\mathbb{S}_{+}^{N}} y^{a}\left|\nabla_{T} u\right|^{2} \mathrm{~d} \sigma}{\int_{\mathbb{S}_{+}^{N}} y^{a} u^{2} \mathrm{~d} \sigma}: u \in H^{1 ; a}\left(\mathbb{S}_{+}^{N}\right), u \equiv 0 \text { on } \mathbb{S}^{N-1} \backslash \omega\right\}, \tag{1.2}
\end{equation*}
$$

where $\nabla_{T} u$ is the tangential gradient of $u$ on $\mathbb{S}_{+}^{N}$. The minimal rate of growth for multi-phase segregation profiles is given by the number

$$
\begin{equation*}
\nu^{\mathrm{ACF}}:=\inf \left\{\frac{\gamma\left(\lambda_{1}^{s}\left(\omega_{1}\right)\right)+\gamma\left(\lambda_{1}^{s}\left(\omega_{2}\right)\right)}{2}: \omega_{1} \cap \omega_{2}=\emptyset\right\} \tag{1.3}
\end{equation*}
$$

where, as usual,

$$
\gamma(t):=\sqrt{\left(\frac{N-2 s}{2}\right)^{2}+t}-\frac{N-2 s}{2}
$$

is defined in such a way that $u$ achieves $\lambda_{1}^{s}(\omega)$ if and only if it is one signed, and its $\gamma\left(\lambda_{1}^{s}(\omega)\right.$ )-homogeneous extension to $\mathbb{R}_{+}^{N+1}$ is $L_{a}$-harmonic. As a peculiar difference with respect to the case $s=1$, we remark that the eigenfunctions achieving $\nu^{\mathrm{ACF}}$ have not disjoint support on the whole $\mathbb{S}_{+}^{N}$, but only on its boundary $\mathbb{S}^{N-1}$. In particular, the degenerate partition $\left(\emptyset, \mathbb{S}^{N-1}\right)$ is admissible, and one can show that it has the same level than the equatorial cut one:

$$
\frac{\gamma\left(\lambda_{1}^{s}(\emptyset)\right)+\gamma\left(\lambda_{1}^{s}\left(\mathbb{S}^{N-1}\right)\right)}{2}=\frac{\gamma\left(\lambda_{1}^{s}\left(\mathbb{S}_{+}^{N-1}\right)\right)+\gamma\left(\lambda_{1}^{s}\left(\mathbb{S}_{-}^{N-1}\right)\right)}{2}=s
$$

As a consequence, the above optimal partition problem does not enjoy the same convexity properties than the one corresponding to $s=1$, and we can only show that

$$
0<\nu^{\mathrm{ACF}} \leq s
$$

Turning to self-segregation, the main point is that the fundamental solution

$$
\Gamma(X)=\frac{C_{N, s}}{|X|^{N-2 s}},
$$

turns out to be bounded near 0 and $H^{1 ; a}(B)$, whenever $s>1 / 2, N=1$. This implies that, when $s>1 / 2, N \geq 2$, the function

$$
v(x, y)=\left(x_{1}^{2}+y^{2}\right)^{(2 s-1) / 2}
$$

is positive and $L_{a}$-harmonic for $y>0, \partial_{\nu}^{a} v(x, 0)=0$ whenever $v(x, 0) \neq 0$, and its trace on $\mathbb{R}^{N}$ has disconnected positivity regions. Moreover, such self-segregated profile is globally Hölder continuous, of exponent $\alpha=2 s-1$ which is arbitrarily small as $s \rightarrow(1 / 2)^{+}$. The phenomenon of self-segregation can be excluded in some situations, for instance when $s \leq 1 / 2$ (for capacitary reasons), or when suitable minimality conditions are imposed (as in [4]). Nonetheless, in general it is hard to tackle: for the case $s=1$ it was excluded only recently, in [11].

To conclude we stress that, by exploiting the compactness provided by Theorem 1.1, the optimal regularity should arise from the classification of suitable blow-down profiles. Also this point presents a number of new difficulties with respect to the case $s=1 / 2$, and it will be the object of a forthcoming paper.

## 2. Monotonicity formulae

This section is devoted to the introduction of some monotonicity formulae, which will provide suitable estimates in order to prove some Liouville type results. Our first aim is to prove monotonicity formulae of Alt-Caffarelli-Friedman type for the one phase problem: these will imply non existence results for $L_{a}$-harmonic functions under different assumptions on their growth at infinity and on the geometry of their null set.

Secondly, we will concentrate on systems of degenerate elliptic equations, providing monotonicity formulae of Alt-Caffarelli-Friedman type with two phases, and of Almgren type.
2.1. One phase Alt-Caffarelli-Friedman formulae. We first deal with $L_{a^{-}}$ harmonic functions (on $\mathbb{R}_{+}^{N+1}$ ) which vanish on the whole $\mathbb{R}^{N}$.

Proposition 2.1. Let $v \in H^{1 ; a}\left(B_{R}^{+}\right)$be a continuous function such that

- $v(x, 0)=0$ for $x \in \mathbb{R}^{N}$;
- for every non negative $\phi \in \mathcal{C}_{0}^{\infty}\left(B_{R}\right)$,

$$
\int_{\mathbb{R}_{+}^{N+1}}\left(L_{a} v\right) v \phi \mathrm{~d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}}\left(\partial_{\nu}^{a} v\right) v \phi \mathrm{~d} x=\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v \cdot \nabla(v \phi) \mathrm{d} x \mathrm{~d} y \leq 0 .
$$

Then the function

$$
\Phi(r):=\frac{1}{r^{4 s}} \int_{B_{r}^{+}} y^{a} \frac{|\nabla v|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y
$$

is monotone non decreasing in $r$ for $r \in(0, R)$.
Remark 2.2. Since

$$
\begin{equation*}
\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v \cdot \nabla(v \phi) \mathrm{d} x \mathrm{~d} y=\int_{\mathbb{R}_{+}^{N+1}} y^{a}\left[|\nabla v|^{2} \phi+\frac{1}{2} \nabla v^{2} \cdot \nabla \phi\right] \mathrm{d} x \mathrm{~d} y \tag{2.1}
\end{equation*}
$$

we have that if $v$ satisfies the assumptions of Proposition 2.1 then also $|v|$ does.

Definition 2.3. We define $\Gamma_{1}^{s} \in \mathcal{C}^{1}\left(\mathbb{R}_{+}^{N+1} ; \mathbb{R}^{+}\right)$as

$$
\Gamma_{1}^{s}(X):= \begin{cases}\frac{1}{|X|^{N-2 s}} & |X| \geq 1 \\ \frac{N+2(1-s)}{2}-\frac{N-2 s}{2}|X|^{2} & |X|<1\end{cases}
$$

We let also $\Gamma_{\varepsilon}^{s}(X)=\Gamma_{1}{ }^{s}(X / \varepsilon) \varepsilon^{2 s-N}$, so that $\Gamma_{\varepsilon}^{s} \nearrow \Gamma^{s}=|X|^{2 s-N}$, a multiple of the fundamental solution of the $s$-laplacian, as $\varepsilon \rightarrow 0$.

Remark 2.4. We observe that each $\Gamma_{\varepsilon}^{s}$ is radial and, in particular, $\partial_{\nu}^{a} \Gamma_{\varepsilon}^{s}=0$ on $\mathbb{R}^{N}$. Moreover, since $N-2 s>0$, they are $L_{a}$-superharmonic on $\mathbb{R}_{+}^{N+1}$.

The proof of Proposition 2.1 is based on the following calculation. Incidentally, we observe that also the following monotonicity results rest on a similar argument.
Lemma 2.5. Let $v$ be as in Proposition 2.1. The function

$$
\begin{equation*}
r \mapsto \int_{B_{r}^{+}} y^{a} \frac{|\nabla v|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y \tag{2.2}
\end{equation*}
$$

is well defined and bounded in any compact subset of $(0,1)$.
Proof. We proceed as follows: let $\varepsilon>0, \delta>0$ and let $\eta_{\delta} \in \mathcal{C}_{0}^{\infty}\left(B_{r+\delta}\right)$ be a smooth, radial cutoff function such that $0 \leq \eta_{\delta} \leq 1$ and $\eta_{\delta}=1$ on $B_{r}$. Choosing $\phi=\eta_{\delta} \Gamma_{\varepsilon}^{s}$ in the second assumption of Proposition 2.1, and recalling equation (2.1), we obtain

$$
\begin{aligned}
& \int_{\mathbb{R}_{+}^{N+1}} y^{a}\left[|\nabla v|^{2} \Gamma_{\varepsilon}^{s}+\frac{1}{2} \nabla v^{2} \cdot \nabla \Gamma_{\varepsilon}^{s}\right] \eta_{\delta} \mathrm{d} x \mathrm{~d} y \leq-\int_{\mathbb{R}_{+}^{N+1}} \frac{1}{2} y^{a} \Gamma_{\varepsilon}^{s} \nabla v^{2} \cdot \nabla \eta_{\delta} \mathrm{d} x \mathrm{~d} y \\
&=\int_{r}^{r+\delta}\left[-\eta_{\delta}^{\prime}(\rho) \int_{\partial^{+} B_{\rho}^{+}} y^{a} \Gamma_{\varepsilon}^{s} v \nabla v \cdot \frac{X}{|X|} \mathrm{d} \sigma\right] \mathrm{d} \rho .
\end{aligned}
$$

Passing to the limit as $\delta \rightarrow 0$ we obtain, for almost every $r \in(0,1)$,

$$
\int_{B_{r}^{+}} y^{a}\left[|\nabla v|^{2} \Gamma_{\varepsilon}^{s}+\frac{1}{2} \nabla(v)^{2} \cdot \nabla \Gamma_{\varepsilon}^{s}\right] \mathrm{d} x \mathrm{~d} y \leq \int_{\partial^{+} B_{r}^{+}} y^{a} \Gamma_{\varepsilon}^{s} v \partial_{\nu} v \mathrm{~d} \sigma
$$

which, combined with the inequality $L_{a} \Gamma_{\varepsilon}^{s} \geq 0$ tested with $v^{2} / 2$ leads to

$$
\int_{B_{r}^{+}} y^{a}|\nabla v|^{2} \Gamma_{\varepsilon}^{s} \mathrm{~d} x \mathrm{~d} y \leq \int_{\partial^{+} B_{r}^{+}} y^{a}\left(\Gamma_{\varepsilon}^{s} v \partial_{\nu} v-\frac{v^{2}}{2} \partial_{\nu} \Gamma_{\varepsilon}^{s}\right) \mathrm{d} \sigma .
$$

Letting $\varepsilon \rightarrow 0^{+}$, by monotone convergence we infer

$$
\begin{equation*}
\int_{B_{r}^{+}} y^{a} \frac{|\nabla v|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y \leq \frac{1}{r^{N-2 s}} \int_{\partial^{+} B_{r}^{+}} y^{a} v \frac{\partial v}{\partial \nu} \mathrm{~d} \sigma+\frac{N-2 s}{2 r^{N+1-2 s}} \int_{\partial^{+} B_{r}^{+}} y^{a} v^{2} \mathrm{~d} \sigma \tag{2.3}
\end{equation*}
$$

and this, in turns, proves the lemma.
Proof of Proposition 2.1. By Remark 2.1 we can assume, without loss of generality, that $v$ is (non trivial and) non negative, and that $R=1$. We start observing that the function $\Phi(r)$ is positive and absolutely continuous for $r \in(0,1)$. Therefore,
the proposition follows once we prove that $\Phi^{\prime}(r) \geq 0$ for almost every $r \in(0,1)$. A direct computation of the logarithmic derivative of $\Phi$ shows that

$$
\frac{\Phi^{\prime}(r)}{\Phi(r)}=-\frac{4 s}{r}+\frac{\int_{+^{+} B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} \sigma}{\int_{B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} x \mathrm{~d} y} .
$$

First we use the estimate (2.3) to bound from below the left hand side:

$$
\begin{aligned}
\frac{\int_{\partial^{+} B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} \sigma}{\int_{B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} x \mathrm{~d} y} & \geq \frac{\int_{\partial^{+} B_{r}^{+}} y^{a}|\nabla v|^{2} \mathrm{~d} \sigma}{\int_{\partial^{+} B_{r}^{+}} v y^{a} \partial_{\nu} v \mathrm{~d} \sigma+(N-2 s) \frac{r}{2} \int_{\partial^{+} B_{r}^{+}} y^{a} v^{2} \mathrm{~d} \sigma} \\
& =\frac{1}{r} \frac{\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|\nabla v^{(r)}\right|^{2} \mathrm{~d} \sigma}{v^{(r)} \xi_{N+1}^{a} \partial_{\nu} v^{(r)} \mathrm{d} \sigma+\frac{N-2 s}{2} \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left(v^{(r)}\right)^{2} \mathrm{~d} \sigma},
\end{aligned}
$$

where $v^{(r)}: \mathbb{S}_{+}^{N-1} \rightarrow \mathbb{R}$ is defined as $v^{(r)}(\xi)=v(r \xi)$, so that $y=r \xi_{N+1}$. We now estimate the right hand side as follows: the numerator writes

$$
\begin{aligned}
& \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|\nabla v^{(r)}\right|^{2} \mathrm{~d} \sigma=\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|\partial_{\nu} v^{(r)}\right|^{2} \mathrm{~d} \sigma+\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|\nabla_{T} v^{(r)}\right|^{2} \mathrm{~d} \sigma \\
& =\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma(\underbrace{\frac{\int_{+}^{N} \xi_{N+1}^{a}\left|\partial_{\nu} v^{(r)}\right|^{2} \mathrm{~d} \sigma}{\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma}}_{t^{2}}+\underbrace{\int_{+}^{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|\nabla_{T} v^{(r)}\right|^{2} \mathrm{~d} \sigma}_{\mathcal{R}} \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma \quad) .
\end{aligned}
$$

where $\mathcal{R}$ stands for the Rayleigh quotient of $v^{(r)}$ on $\mathbb{S}_{+}^{N}$. On the other hand, by the Cauchy-Schwarz inequality, the denominator may be estimated from above by

$$
\begin{aligned}
& \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a} v^{(r)} \partial_{\nu} v^{(r)} \mathrm{d} \sigma+\frac{N-2 s}{2} \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma \\
& \leq\left(\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma\right)^{1 / 2}\left(\int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a} \partial_{\nu} v^{(r)} \mathrm{d} \sigma\right)^{1 / 2}+\frac{N-2 s}{2} \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma \\
& \leq \int_{\mathbb{S}_{+}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma \\
& {[\underbrace{\left(\int_{\mathbb{S}_{+}^{N}}^{\int_{N+1}^{N}} \xi_{N+1}^{a}\left|v^{(r)}\right|^{2} \mathrm{~d} \sigma\right.}_{t})^{a}} \\
&
\end{aligned}
$$

As a consequence

$$
\begin{equation*}
\frac{\int_{\partial^{+} B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} \sigma}{\int_{B_{r}^{+}} y^{a}|\nabla v|^{2} /|X|^{N-2 s} \mathrm{~d} x \mathrm{~d} y} \geq \frac{1}{r} \min _{t \in \mathbb{R}^{+}} \frac{\mathcal{R}+t^{2}}{t+\frac{N-2 s}{2}} . \tag{2.4}
\end{equation*}
$$

A simple computation shows that the minimum is achieved when

$$
t=\gamma(\mathcal{R})=\sqrt{\left(\frac{N-2 s}{2}\right)^{2}+\mathcal{R}}-\frac{N-2 s}{2}
$$

and it is equal to $2 \gamma(\mathcal{R})$. Recalling the definition of $\lambda_{1}^{s}(\emptyset)$ (equation (1.2)) we obtain

$$
\frac{\Phi^{\prime}(r)}{\Phi(r)}+\frac{4 s}{r} \geq \frac{2}{r} \gamma\left(\lambda_{1}^{s}(\emptyset)\right)
$$

and the proposition follows observing that $\lambda_{1}^{s}(\emptyset)$ is achieved by $v(x, y)=y^{2 s}$, in such a way that

$$
\gamma\left(\lambda_{1}^{s}(\emptyset)\right)=2 s
$$

Now we turn to functions which vanish only on a half space.
Proposition 2.6. Let $v \in H^{1 ; a}\left(B_{R}^{+}\right)$be a continuous function such that

- $v(x, 0)=0$ for $x_{1} \leq 0$;
- for every non negative $\phi \in \mathcal{C}_{0}^{\infty}\left(B_{R}\right)$,

$$
\int_{\mathbb{R}_{+}^{N+1}}\left(L_{a} v\right) v \phi \mathrm{~d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}}\left(\partial_{\nu}^{a} v\right) v \phi \mathrm{~d} x=\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v \cdot \nabla(v \phi) \mathrm{d} x \mathrm{~d} y \leq 0 .
$$

Then the function

$$
\Phi(r):=\frac{1}{r^{2 s}} \int_{B_{r}^{+}} y^{a} \frac{|\nabla v|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y
$$

is monotone non decreasing in $r$ for $r \in(0, R)$.
Proof. The proof follows the line of the one of Proposition 2.1, recalling that

$$
v(x, y)=\left(\frac{\sqrt{x_{1}^{2}+y^{2}}+x_{1}}{2}\right)^{s}
$$

achieves $\gamma\left(\lambda_{1}^{s}\left(\mathbb{S}^{N-1} \cap\left\{x_{1}>0\right\}\right)\right)=s$ (see, for instance, [5, page 442]).
In the previous propositions, we considered functions vanishing on the whole $\mathbb{R}^{N}$, or on a half-space. Now, in great contrast with the case $s \leq 1 / 2$, it is known that, if $s>1 / 2$, then also $(N-1)$-dimensional subsets may have positive capacity. This motivates the following formula, which is the analogous of the previous ones, for functions which vanish on subspaces of $\mathbb{R}^{N}$ of codimension 1 .

Proposition 2.7. Let $s>1 / 2$ and let $v \in H^{1 ; a}\left(B_{R}^{+}\right)$be a continuous function such that

- $v(x, 0)=0$ for $x_{1}=0$;
- for every non negative $\phi \in \mathcal{C}_{0}^{\infty}\left(B_{R}\right)$,

$$
\int_{\mathbb{R}_{+}^{N+1}}\left(L_{a} v\right) v \phi \mathrm{~d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}}\left(\partial_{\nu}^{a} v\right) v \phi \mathrm{~d} x=\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v \cdot \nabla(v \phi) \mathrm{d} x \mathrm{~d} y \leq 0 .
$$

Then the function

$$
\Phi(r):=\frac{1}{r^{4 s-2}} \int_{B_{r}^{+}} y^{a} \frac{|\nabla v|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y
$$

is monotone non decreasing in $r$ for $r \in(0, R)$.
Proof. Let $\bar{\omega}=\mathbb{S}^{N-1} \backslash\left\{x_{1}=0\right\}$, and let us consider the function

$$
v(x, y)=\left|\left(x_{1}, 0, y\right)\right|^{2 s-1}
$$

that is the fundamental solution in dimension 1, extended in a constant way to the other directions. Then $v$ is $(2 s-1)$-homogeneous, positive and $L_{a}$-harmonic for $y>0$. We deduce that its restriction to $\partial^{+} B_{1}^{+}=\mathbb{S}_{+}^{N}$ is an eigenfunction associated to $\lambda_{1}^{s}(\bar{\omega})$, so that

$$
\gamma\left(\lambda_{1}^{s}(\bar{\omega})\right)=2 s-1
$$

As a consequence, also in this case the proposition follows by reasoning as in the proof of Proposition 2.1.
2.2. Two phases Alt-Caffarelli-Friedman monotonicity formulae. Now we turn to the multi-component ACF formulae. We start by proving that the constant $\nu^{\mathrm{ACF}}$ defined in equation (1.3) is not 0 .

Lemma 2.8. For any $N \geq 2,0<\nu^{\mathrm{ACF}} \leq s$.
Proof. The bound from above easily follows by comparing with the value corresponding to the partition $\left(\mathbb{S}^{N-1}, \emptyset\right)$ : indeed, it holds $\lambda_{1}^{s}\left(\mathbb{S}^{N-1}\right)=0$, achieved by $u(x, y) \equiv 1$, and $\lambda_{1}^{s}(\emptyset)=2 s N$, achieved by $u(x, y)=y^{1-a}$. In order to prove the estimate from below, one can argue by contradiction, as in the proof of [19, Lemma 2.5], exploiting the compactness both of the embedding $H^{1 ; a}\left(\mathbb{S}_{+}^{N}\right) \hookrightarrow L^{2 ; a}\left(\mathbb{S}_{+}^{N}\right)$ and of the trace operator from $H^{1 ; a}\left(\mathbb{S}_{+}^{N}\right)$ to $L^{2}\left(\mathbb{S}^{N-1}\right)$.

We will prove two multi-component formulae, the first regarding entire profiles which are segregated on $\mathbb{R}^{N}$, the second regarding profiles which coexist on $\mathbb{R}^{N}$.
Proposition 2.9. Let $v_{1}, v_{2} \in H^{1 ; a}\left(B_{R}^{+}\left(x_{0}, 0\right)\right)$ be continuous functions such that

- $\left.v_{1} v_{2}\right|_{\{y=0\}}=0, v_{i}\left(x_{0}, 0\right)=0$;
- for every non negative $\phi \in \mathcal{C}_{0}^{\infty}\left(B_{R}\left(x_{0}, 0\right)\right)$,

$$
\int_{\mathbb{R}_{+}^{N+1}}\left(L_{a} v_{i}\right) v_{i} \phi \mathrm{~d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}}\left(\partial_{\nu}^{a} v_{i}\right) v_{i} \phi \mathrm{~d} x=\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v_{i} \cdot \nabla\left(v_{i} \phi\right) \mathrm{d} x \mathrm{~d} y \leq 0 .
$$

Then the function

$$
\Phi(r):=\prod_{i=1}^{2} \frac{1}{r^{2 \nu^{\mathrm{ACF}}}} \int_{B_{r}^{+}\left(x_{0}, 0\right)} y^{a} \frac{\left|\nabla v_{i}\right|^{2}}{|X|^{N-2 s}} \mathrm{~d} x \mathrm{~d} y
$$

is monotone non decreasing in $r$ for $r \in(0, R)$.

Proof. Applying the same estimates developed for the proof of Proposition 2.1, it is easy to see that the proposition is equivalent to (summing equation (2.4) for the two functions)

$$
\Phi^{\prime}(r) \geq 0 \Leftrightarrow \sum_{i=1}^{2} \frac{\int_{+^{+} B_{r}^{+}} y^{a} \frac{\left|\nabla v_{i}\right|^{2}}{|X|^{N-1}} \mathrm{~d} \sigma}{\int_{B_{r}^{+}} y^{a} \frac{\left|\nabla v_{i}\right|^{2}}{|X|^{N-1}} \mathrm{~d} x \mathrm{~d} y} \geq \frac{2}{r} \inf _{\left(\omega_{1}, \omega_{2}\right) \in \mathcal{P}^{2}} \sum_{i=1}^{2} \gamma\left(\lambda_{1}^{s}\left(\omega_{i}\right)\right)=\frac{4}{r} \nu^{\mathrm{ACF}}
$$

In particular, the last inequality follows by the definition of $\nu^{\mathrm{ACF}}$.
Proposition 2.10. Let $v_{1}, v_{2} \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ be continuous functions such that, for every non negative $\phi \in \mathcal{C}_{0}^{\infty}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ and $j \neq i$,

$$
\begin{aligned}
\int_{\mathbb{R}_{+}^{N+1}}\left(L_{a} v_{i}\right) v_{i} \phi \mathrm{~d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}}\left(\partial_{\nu}^{a} v_{i}\right. & \left.+a_{i j} v_{i} v_{j}^{2}\right) v_{i} \phi \mathrm{~d} x \\
& =\int_{\mathbb{R}_{+}^{N+1}} y^{a} \nabla v_{i} \cdot \nabla\left(v_{i} \phi\right) \mathrm{d} x \mathrm{~d} y+\int_{\mathbb{R}^{N}} a_{i j} v_{i}^{2} v_{j}^{2} \phi \mathrm{~d} x \leq 0 .
\end{aligned}
$$

For any $\nu^{\prime} \in\left(0, \nu^{\mathrm{ACF}}\right)$ there exists $\bar{r}>1$ such that the function

$$
\Phi(r):=\prod_{i=1}^{2} \Phi_{i}(r)
$$

is monotone non decreasing in $r$ for $r \in(\bar{r}, \infty)$, where

$$
\Phi_{i}(r):=\frac{1}{r^{2 \nu^{\prime}}}\left(\int_{B_{r}^{+}} y^{a}\left|\nabla v_{i}\right|^{2} \Gamma_{1} \mathrm{~d} x \mathrm{~d} y+\int_{\partial^{0} B_{r}^{+}} a_{i j} v_{i}^{2} v_{j}^{2} \Gamma_{1} \mathrm{~d} x\right), \quad \text { for } j \neq i
$$

The proof of Proposition 2.10 is based on a contradiction argument, and follows the lines of the one of Proposition 2.9. We do not report the details, referring the reader to [14, Lemma 2.5] and [19, Theorem 2.13], where similar computations were developed for the case $s=1$ and $s=1 / 2$, respectively.
2.3. Almgren type monotonicity formula. To conclude this section on monotonicity formulae, we focus our attention on an Almgren quotient defined for a suitable class a functions: these will come into play as limits of a blow up sequence. First, for any

$$
\mathbf{v} \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right):=\left\{v: \forall D \subset \mathbb{R}^{N+1} \text { open and bounded, }\left.v\right|_{D^{+}} \in H^{1 ; a}\left(D^{+}\right)\right\}
$$

$\mathbf{v}=\left(v_{1}, \ldots, v_{k}\right)$ continuous, let use define

$$
\begin{aligned}
E\left(x_{0}, r\right) & :=\frac{1}{r^{N-2 s}} \int_{B_{r}^{+}\left(x_{0}, 0\right)} y^{a} \sum_{i}\left|\nabla v_{i}\right|^{2} \mathrm{~d} x \mathrm{~d} y \\
H\left(x_{0}, r\right) & :=\frac{1}{r^{N+1-2 s}} \int_{\partial^{+} B_{r}^{+}\left(x_{0}, 0\right)} y^{a} \sum_{i} v_{i}^{2} \mathrm{~d} \sigma
\end{aligned}
$$

where $x_{0} \in \mathbb{R}^{N}$ and $r>0$. By assumption, both $E$ and $H$ are locally absolutely continuous functions on $(0,+\infty)$, that is, both $E^{\prime}$ and $H^{\prime}$ are $L_{\mathrm{loc}}^{1}(0, \infty)$ (here, $'=\mathrm{d} / \mathrm{d} r)$. Let us also consider the function (Almgren frequency function)

$$
N\left(x_{0}, r\right):=\frac{E\left(x_{0}, r\right)}{H\left(x_{0}, r\right)}
$$

We have the following result, which proof we omit since it follows with minor changes from the one of Theorem 3.3 in [19].

Proposition 2.11. Let $\mathbf{v} \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}} ; \mathbb{R}^{k}\right)$, $\mathbf{v}=\left(v_{1}, \ldots, v_{k}\right)$ continuous, and let us assume that:
(1) $\left.v_{i} v_{j}\right|_{y=0}=0$ for every $j \neq i$;
(2) for every $i$,

$$
\begin{cases}L_{a} v_{i}=0 & \text { in } \mathbb{R}_{+}^{N+1}  \tag{2.5}\\ v_{i} \partial_{\nu}^{a} v_{i}=0 & \text { on } \mathbb{R}^{N} \times\{0\}\end{cases}
$$

(3) for any $x_{0} \in \mathbb{R}^{N}$ and a.e. $r>0$, the following (Pohozaev type) identity holds
$(2 s-N) \int_{B_{r}^{+}} y^{a} \sum_{i}\left|\nabla v_{i}\right|^{2} \mathrm{~d} x \mathrm{~d} y+r \int_{\partial^{+} B_{r}^{+}} y^{a} \sum_{i}\left|\nabla v_{i}\right|^{2} \mathrm{~d} \sigma=2 r \int_{\partial^{+} B_{r}^{+}} y^{a} \sum_{i}\left|\partial_{\nu} v_{i}\right|^{2} \mathrm{~d} \sigma$.
Then for every $x_{0} \in \mathbb{R}^{N}$ the Almgren frequency function $N\left(x_{0}, r\right)$ is well defined on $(0, \infty)$, absolutely continuous, non decreasing, and it satisfies the identity

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} r} \log H(r)=\frac{2 N(r)}{r} \tag{2.6}
\end{equation*}
$$

Moreover, if $N(r) \equiv \gamma$ on an open interval, then $N \equiv \gamma$ for every $r$, and $\mathbf{v}$ is a homogeneous function of degree $\gamma$.

Of the many consequences that the validity of an Almgren monotonicity formula carries, at this stage we are mostly interested in the following, which states a rigidity property implied by Hölder continuity.

Corollary 2.12. If $\mathbf{v}$ satisfies the assumptions of Proposition 2.11 and is globally Hölder continuous of exponent $\gamma$ on $\mathbb{R}_{+}^{N+1}$, then it is homogeneous of degree $\gamma$ with respect to any of its (possible) zeroes, and thus

$$
\mathcal{Z}:=\left\{x \in \mathbb{R}^{N}: \mathbf{v}(x, 0)=0\right\} \quad \text { is an affine subspace of } \mathbb{R}^{N} .
$$

Proof. The proof relies on the fact that the Almgren centered at any point of $\mathcal{Z}$ has to be constant and equal to $\gamma$. Indeed letting $x_{0} \in \mathcal{Z}$, we argue by contradiction and suppose that $N\left(x_{0}, R\right)>\gamma$ for some $R$. By monotonicity of $N$ we have

$$
\frac{\mathrm{d}}{\mathrm{~d} r} \log H(r) \geq \frac{2}{r} N\left(x_{0}, R\right) \quad \forall r \geq R
$$

and, integrating in $(R, r)$, we find

$$
C r^{2 N\left(x_{0}, R\right)} \leq H(r) \leq C r^{2 \gamma}
$$

a contradiction for $r$ large enough. The same reasoning provides a contradiction in the case $N\left(x_{0}, R\right)<\gamma$ and $r \leq R$.

## 3. LIOUVILLE TYPE RESULTS

Relying on the previous monotonicity formulae, in this section we will prove some Liouville type theorems for solution to either equations or systems involving the operator $L_{a}$. As a first result, we have the following.

Proposition 3.1. Let $v \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ be continuous and satisfy

$$
\begin{cases}L_{a} v=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ v(x, 0)=0 & \text { on } \mathbb{R}^{N}\end{cases}
$$

and let us suppose that for some $\gamma \in[0,2 s), C>0$ it holds

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$. Then $v$ is identically zero.
Proof. We remark that $v$ satisfies the assumptions of Proposition 2.1 for any $R$. For $r>0$ large enough, we choose $\eta$ non negative, smooth and radial cut-off function supported in $B_{2 r}^{+}$with $\eta=1$ in $B_{r}^{+}$such that

$$
\int_{\mathbb{R}_{+}^{N+1}} y^{a}|\nabla \eta| \leq C r^{N+1-2 s}, \quad \int_{\mathbb{R}_{+}^{N+1}}\left|L_{a} \eta\right| \leq C r^{N-2 s}
$$

(for instance, we can take $\eta$ as a smooth approximation of the function $\frac{1}{r}(2 r-|X|)$ in $B_{2 r} \backslash B_{r}$ ). Moreover, let $\Gamma_{1}^{s}$ be defined as in Definition 2.3 (in particular, it is radial and superharmonic). Testing the equation for $v$ with $\Gamma_{1}^{s} v \eta$ we obtain

$$
\int_{B_{2 r}^{+}} y^{a}|\nabla v|^{2} \Gamma_{1}^{s} \eta \mathrm{~d} x \mathrm{~d} y \leq \int_{B_{2 r}^{+} \backslash B_{r}^{+}} \frac{1}{2} v^{2}\left[-L_{a} \eta \Gamma_{1}^{s}+2 y^{a} \nabla \eta \cdot \nabla \Gamma_{1}^{s}\right] \mathrm{d} x \mathrm{~d} y
$$

where we used that $\eta$ is constant in $B_{r}^{+}$. Since $\Gamma_{1}^{s}(X)=|X|^{2 s-N}$ outside $B_{1}$, and $|v(X)| \leq C r^{\gamma}$ outside a suitable $B_{\bar{r}}$, using the notations of Proposition 2.1 we infer

$$
\Phi(r)=\frac{1}{r^{4 s}}\left(\int_{B_{r}^{+}} y^{a}|\nabla v|^{2} \Gamma_{1}^{s} \mathrm{~d} x \mathrm{~d} y\right) \leq \frac{1}{r^{4 s}} \cdot C r^{2 \gamma}
$$

with $C$ independent of $r>\bar{r}$. Due to the monotonicity of $\Phi$, we then find

$$
0 \leq \Phi(\bar{r}) \leq C r^{2(\gamma-2 s)}
$$

for every $r>\bar{r}$ sufficiently large. This forces $v$ to be constant.
The previous proposition allows to prove an analogous result of the classical Liouville Theorem, which holds for $L_{a}$-harmonic functions.
Proposition 3.2. Let $v$ be an entire $L_{a}$-harmonic function defined on $\mathbb{R}^{N+1}$. If there exists $\gamma<1$ such that

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

then $\left.v\right|_{y=0}$ is constant. Moreover, if $\gamma<\min (2 s, 1)$, then $v$ is constant.

Proof. It is well known (see [5]) that $L_{a}$-harmonic functions enjoy the mean value property $(C>0)$

$$
v(x, 0)=\frac{C}{r^{N+a}} \int_{\partial B_{r}(x, 0)}|y|^{a} v \mathrm{~d} \sigma
$$

and, equivalently

$$
v(x, 0)=\frac{C}{R^{N+1+a}} \int_{B_{R}(x, 0)}|y|^{a} v \mathrm{~d} \sigma .
$$

It follows, by the growth condition, that

$$
\begin{aligned}
\left|v\left(x^{\prime}, 0\right)-v\left(x^{\prime \prime}, 0\right)\right| & \leq \frac{C}{R^{N+1+a}} \int_{B_{R}\left(x^{\prime}, 0\right) \triangle B_{R}\left(x^{\prime \prime}, 0\right)} y^{a}|v(x, y)| \mathrm{d} x \mathrm{~d} y \\
& \leq \frac{C}{R^{N+1+a}} \int_{B_{R}\left(x^{\prime}, 0\right) \triangle B_{R}\left(x^{\prime \prime}, 0\right)} y^{a}|X|^{\gamma} \mathrm{d} x \mathrm{~d} y \leq C R^{\gamma-1}
\end{aligned}
$$

and the first conclusion follows since $\gamma<1$. Let us now assume $\gamma<\min (2 s, 1)$ : since $\left.v\right|_{y=0}$ is constant, we can assume $\left.v\right|_{y=0} \equiv 0$ and apply Proposition 3.1.

We can obtain the analogous of the classical Liouville Theorem for $s$-harmonic functions by applying the previous result to the even reflection through $\{y=0\}$ of their $L_{a}$-harmonic extensions.
Corollary 3.3. Let $v \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ be continuous and satisfy

$$
\begin{cases}L_{a} v=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} v(x, 0)=0 & \text { on } \mathbb{R}^{N}\end{cases}
$$

and let us suppose that for some $\gamma<\min (2 s, 1), C>0$ it holds

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$. Then $v$ is constant.
By the way, a stronger result in the direction of the above corollary is contained in [5, Lemma 2.7].

In the same spirit of Proposition 3.1, we provide a result concerning $L_{a}$-harmonic functions which vanish on a half space of $\mathbb{R}^{N}$.
Proposition 3.4. Let $v \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ satisfy the assumptions of Proposition 2.6. Let us suppose that for some $\gamma \in[0, s), C>0$ it holds

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$. Then $v$ is identically zero.
Proof. Again, $v$ as above fulfills the assumptions of Proposition 2.6. Now, assuming that $v$ is not constant, we can argue as in the proof of Proposition 3.9 obtaining a contradiction.

We proceed with a lemma regarding the decay of subsolutions to a linear equation involving $L_{a}$.

Lemma 3.5. Let $M>0$ and $\delta>0$ be fixed and let $h \in L^{\infty}\left(\partial^{0} B_{1}^{+}\right)$with $\|h\|_{L^{\infty}} \leq \delta$. Any $v \in H^{1 ; a}\left(B_{1}^{+}\right)$non negative solution to

$$
\begin{cases}L_{a} v \leq 0 & \text { in } B_{1}^{+} \\ \partial_{\nu}^{a} v \leq-M v+h & \text { on } \partial^{0} B_{1}^{+}\end{cases}
$$

verifies

$$
\sup _{\partial^{0} B_{1 / 2}^{+}} \leq \frac{1+\delta}{M} \sup _{\partial^{+} B_{1}^{+}} v
$$

The proof of Lemma 3.5 follows by a comparison argument. In order to construct an appropriate supersolution, we need a technical lemma. Let $f \in A C(\mathbb{R}) \cap \mathcal{C}^{\infty}(\mathbb{R})$ be defined as

$$
f(x)=C \int_{-\infty}^{x} \frac{1}{\left(1+t^{2}\right)^{1-a / 2}} \mathrm{~d} t
$$

where $C$ is such that $f(+\infty)=1$.
Lemma 3.6. There exists $c>0$ such that

$$
(-\Delta)^{s} f(x) \geq-c f(x)
$$

for any $x<0$.
Proof. The function $f$ under consideration is increasing, smooth and such that there exist $c, C>0$ with

$$
\lim _{|t| \rightarrow \infty} f^{\prime}(t)|t|^{2-a}=C>0 \quad \text { and } \quad \lim _{|t| \rightarrow \infty} f^{\prime \prime}(t)|t|^{3-a}=c
$$

The $s$-laplacian of the function $f$ is well-defined. Thanks to the extension representation of the fractional laplacian, we can consider

$$
\begin{aligned}
v(x, y) & =\int_{\mathbb{R}} P_{a}(\xi, y) f(x-\xi) \mathrm{d} \xi=\int_{\mathbb{R}} y^{1-a} \frac{f(x-\xi)}{\left(\xi^{2}+y^{2}\right)^{1-a / 2}} \mathrm{~d} \xi \\
& =\{t=\xi / y\}=\int_{\mathbb{R}} \frac{f(x-t y)}{\left(1+t^{2}\right)^{1-a / 2}} \mathrm{~d} t
\end{aligned}
$$

so that

$$
\begin{aligned}
\partial_{\nu}^{a} v(x, 0) & =\lim _{y \rightarrow 0^{+}}-y^{a} \frac{\partial}{\partial y} \int \frac{f(x-t y)}{\left(1+t^{2}\right)^{1-a / 2}} \mathrm{~d} t=\lim _{y \rightarrow 0^{+}} \int y^{a} t \frac{f^{\prime}(x-t y)}{\left(1+t^{2}\right)^{1-a / 2}} \mathrm{~d} t \\
& =\{r=y t\}=\lim _{y \rightarrow 0^{+}} \int \frac{r}{\left(y^{2}+r^{2}\right)^{1-a / 2}} f^{\prime}(x-r) \mathrm{d} r \\
& =\operatorname{pv} \int \frac{|r|^{a}}{r} f^{\prime}(x-r) \mathrm{d} r=\operatorname{pv} \int \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r .
\end{aligned}
$$

Let us observe that, due to the decay properties of $f^{\prime}$ at infinity, the last principal value acts only around the singularity $x=r$, that is

$$
(-\Delta)^{s} f(x)=\lim _{\varepsilon \rightarrow 0^{+}} \int_{\mathbb{R} \backslash(r-\varepsilon, r+\varepsilon)} \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r .
$$

We aim at proving that there exists a positive $c>0$ such that the estimate

$$
(-\Delta)^{s} f(x) \geq-c f(x)
$$

holds for every $x \leq 0$. As a first step, we are going to estimate the asymptotic behavior of the right hand side as $x \rightarrow-\infty$. To this end, letting $K>0$ be a fixed number, we write

$$
\begin{equation*}
(-\Delta)^{s} f(x)=\operatorname{pv} \int_{-\infty}^{-K} \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r+\int_{-K}^{\infty} \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r \tag{3.1}
\end{equation*}
$$

(this decomposition is possible thanks to the prescribed decay of $f^{\prime}$ ). We estimate the two contributions separately. First $(a<1)$

$$
\int_{-K}^{\infty} \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r \geq-(-K-x)^{a-1} \int_{-K}^{\infty} f^{\prime}(r) \mathrm{d} r \geq-C|x|^{a-1}
$$

We further decompose the second integral in (3.1), to find

$$
\begin{array}{r}
\text { pv } \int_{-\infty}^{-K} \frac{|x-r|^{a}}{x-r} f^{\prime}(r) \mathrm{d} r=\{t=r /|x|\}=-|x|^{a} \mathrm{pv} \int_{-\infty}^{-K /|x|} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|) \mathrm{d} t \\
=-|x|^{a}\left[\int_{-\infty}^{-3 / 2} \ldots \mathrm{~d} t+\mathrm{pv} \int_{-3 / 2}^{-1 / 2} \ldots \mathrm{~d} t+\int_{-1 / 2}^{-K /|x|} \ldots \mathrm{d} t\right]
\end{array}
$$

In the first part we use the estimate

$$
f^{\prime}(t|x|) \geq c|t|^{a-2}|x|^{a-2}
$$

in order to obtain

$$
-|x|^{a} \int_{-\infty}^{-3 / 2} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|) \mathrm{d} t \geq-c|x|^{2 a-2} \int_{-\infty}^{-3 / 2} \frac{|1+t|^{a}}{1+t}|t|^{a-2} \mathrm{~d} t \geq-C|x|^{2 a-2}
$$

In the principal value we write

$$
-|x|^{a} \mathrm{pv} \int_{-3 / 2}^{-1 / 2} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|) \mathrm{d} t=-|x|^{2 a-2} \mathrm{pv} \int_{-3 / 2}^{-1 / 2} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|)|x|^{2-a} \mathrm{~d} t
$$

Since

$$
f^{\prime}(t|x|)|x|^{2-a} \rightarrow C|t|^{a-2} \quad \text { in } \mathcal{C}^{1}\left(-\frac{3}{2},-\frac{1}{2}\right) \text { as }|x| \rightarrow \infty
$$

and

$$
\operatorname{pv} \int_{-3 / 2}^{-1 / 2} \frac{|1+t|^{a}}{1+t}|t|^{a-2} \mathrm{~d} t=\{r=-1-t\}=\mathrm{pv} \int_{-1 / 2}^{1 / 2}-\frac{|r|^{a}}{r}(r+1)^{a-2} \mathrm{~d} r>0
$$

we obtain the lower bound

$$
-|x|^{a} \text { pv } \int_{-3 / 2}^{-1 / 2} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|) \mathrm{d} t \geq-C|x|^{2 a-2}
$$

To estimate the last integral we use

$$
f^{\prime}(t|x|) \leq C|t|^{a-2}|x|^{a-2}
$$

to obtain

$$
\begin{aligned}
&-|x|^{a} \int_{-1 / 2}^{-K /|x|} \frac{|1+t|^{a}}{1+t} f^{\prime}(t|x|) \mathrm{d} t \geq-C|x|^{2 a-2} \int_{-1 / 2}^{-K /|x|} \frac{|1+t|^{a}}{1+t}|t|^{a-2} \mathrm{~d} t \\
& \geq-C|x|^{2 a-2}\left(1+\frac{1}{|x|^{a-1}}\right) \geq-C|x|^{a-1}
\end{aligned}
$$

As a consequence

$$
(-\Delta)^{s} f(x) \geq-C\left(|x|^{a-1}+|x|^{2 a-2}\right) \geq-C|x|^{a-1}
$$

On the other hand, by a direct estimate we have $(x \ll 0)$

$$
f(x) \leq C \frac{1}{|x|^{1-a}}
$$

which immediately yields that for $x \ll 0$ there exists $c>0$ such that

$$
(-\Delta)^{s} f(x) \geq-c f(x)
$$

Due to the positivity and regularity of $f$, this estimates extends to every $x \leq 0$.
We can conclude with the proof of Lemma 3.5.
Proof of Lemma 3.5. Let us first consider, for $M>0$, the scaling $x \mapsto M^{1 / 2 s} x$ and let us introduce the function $f_{M}(x):=f\left(M^{1 / 2 s} x\right)$. It follows that

$$
(-\Delta)^{s} f_{M}(x)=M^{2 s / 2 s}\left[(-\Delta)^{s} f\right]\left(M^{1 / 2 s} x\right) \geq-c M f_{M}(x)
$$

It is then clear that if we let

$$
g_{M}(x):=f_{M}(t-1)+f_{M}(-t-1)
$$

then for any $M>0$ it holds

$$
\begin{cases}(-\Delta)^{s} g_{M}(x) \geq-c M g_{M}(x) & \text { in }(-1,1) \\ g_{M}(x) \geq \frac{1}{2} & \text { in } \mathbb{R} \backslash(-1,1) \\ g_{M}(x) \leq C M^{-1} & \text { in }\left(-\frac{1}{2}, \frac{1}{2}\right)\end{cases}
$$

The proof follows by a comparison argument between $v$ and the supersolution

$$
w_{\delta}:=\delta \frac{1}{M}+\int_{\mathbb{R}} P_{a}(\xi, y) g_{M}(x-\xi) \mathrm{d} \xi
$$

The previous estimate allows to prove the following.
Proposition 3.7. Let $v$ satisfy

$$
\begin{cases}L_{a} v=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} v=-\lambda v & \text { on } \mathbb{R}^{N}\end{cases}
$$

for some $\lambda>0$ and let us suppose that for some $\gamma<\min (1,2 s), C>0$ it holds

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$. Then $v$ is constant.
Proof. Let either $z=v^{+}$or $z=v^{-}$. In both cases,

$$
\begin{cases}L_{a} z \leq 0, & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} z \leq-\lambda z, & \text { on } \mathbb{R}^{N}\end{cases}
$$

By translating and scaling, Lemma 3.5 implies that

$$
z\left(x_{0}, 0\right) \leq \sup _{\partial^{0} B_{r / 2}\left(x_{0}, 0\right)} z \leq \frac{1}{\lambda r} \sup _{\partial^{+} B_{r}\left(x_{0}, 0\right)} z \leq C \frac{1+r^{\gamma}}{r}
$$

Letting $r \rightarrow \infty$ the proposition follows.

Proposition 3.8. Let $v$ satisfy

$$
\begin{cases}L_{a} v=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} v=\lambda & \text { on } \mathbb{R}^{N}\end{cases}
$$

for some $\lambda \in \mathbb{R}$ and let us suppose that for some $\gamma<\min (1,2 s), C>0$ it holds

$$
|v(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$. Then $v$ is constant.
Proof. For $h \in \mathbb{R}^{N}$, let $w(x, y):=v(x+h, y)-v(x, y)$. Then $w$ solves

$$
\begin{cases}L_{a} w=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} w=0 & \text { on } \mathbb{R}^{N}\end{cases}
$$

and, as usual, we can reflect and use the growth condition to infer that $w$ has to be constant, that is $v(x+h, y)=c_{h}+v(x, y)$. Deriving the previous expression in $x_{i}$, we find that

$$
v(x, y)=\sum_{i=1}^{k} c_{i}(y) x_{i}+c_{0}(y)
$$

Using again the growth condition, we see that $c_{i} \equiv 0$ for $i=1, \ldots, k$, while $c_{0}$ is constant. We observe that, consequently, $\lambda=0$.

Proposition 3.9. Let $\mathbf{v} \in H_{\mathrm{loc}}^{1 ; a}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ be continuous and satisfy

$$
\begin{cases}L_{a} v_{i}=0 & \text { in } \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} v_{i}=-v_{i} \sum_{j \neq i} a_{i j} v_{j}^{2} & \text { on } \mathbb{R}^{N}\end{cases}
$$

and let $\nu^{\mathrm{ACF}}$ be defined according to (1.3). If for some $\gamma \in\left(0, \nu^{\mathrm{ACF}}\right)$ there exists $C$ such that

$$
|\mathbf{v}(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$, then $k-1$ components of $\mathbf{v}$ annihilate and the last is constant.
Proof. We only sketch the proof, referring to [19, Proposition 4.1] for a detailed proof in the case $s=1 / 2$. To start with, we observe that any pair of components of $\mathbf{v}$ satisfy the assumptions of Proposition 2.10; as a consequence, if $\mathbf{v}$ had two nontrivial components, then one could argue as in the proof of Proposition 3.1 in order to obtain a contradiction. Once we know that all but one component are trivial, we can conclude by applying Corollary 3.3 to the last one.

Proposition 3.10. Let $\mathbf{v}$ satisfy the assumptions of Proposition 2.11 and $\gamma \in$ $\left(0, \nu^{\mathrm{ACF}}\right)$.
(1) If there exists $C$ such that

$$
|\mathbf{v}(X)| \leq C\left(1+|X|^{\gamma}\right)
$$

for every $X$, then $k-1$ components of $\mathbf{v}$ annihilate;
(2) if furthermore $\mathbf{v} \in \mathcal{C}^{0, \gamma}\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ and

$$
\gamma< \begin{cases}\nu^{\mathrm{ACF}} & 0<s \leq \frac{1}{2} \\ \min \left(\nu^{\mathrm{ACF}}, 2 s-1\right) & \frac{1}{2}<s<1\end{cases}
$$

then the only possibly nontrivial component is constant.
Proof. To prove 1., we can reason as in the proof of Proposition 3.9, using Proposition 2.9 instead of Proposition 2.10. Turning to 2 ., let $v$ denote the only non trivial component. If $v(x, 0) \neq 0$ for every $x$, then we deduce that $\partial_{\nu}^{a} v(x, 0) \equiv 0$, and we can conclude by using Corollary 3.3. On the other hand, let

$$
\mathcal{Z}=\left\{x \in \mathbb{R}^{N}: v(x, 0)=0\right\} \neq \emptyset .
$$

By Corollary 2.12, we have that $v$ is $\gamma$-homogeneous about any point of $\mathcal{Z}$, which is then an affine subspace of $\mathbb{R}^{N}$, and that $v$ solves

$$
\begin{cases}L_{a} v=0 & \text { in } \mathbb{R}_{+}^{N+1}  \tag{3.2}\\ v=0 & \text { on } \mathcal{Z} \\ \partial_{\nu}^{a} v=0 & \text { on } \mathbb{R}^{N} \backslash \mathcal{Z}\end{cases}
$$

Now, if $\mathcal{Z}=\mathbb{R}^{N}$, then Proposition 3.1 applies. On the other hand, if $\operatorname{dim} \mathcal{Z} \leq$ $N-2 s$, we obtain that $\mathcal{Z}$ has null $L_{a}$-capacity (this can be seen directly for the fractional laplacian in $\mathbb{R}^{N}$, see for instance [13, Theorem 3.14]), and the conclusion follows by Proposition 3.2. Finally, we are left to deal with the case

$$
\operatorname{dim} \mathcal{Z}=N-1 \quad \text { and } \quad \frac{1}{2}<s<1
$$

In this situation, the previous capacitary reasoning fails, see Remark 3.11 below. Nonetheless, assuming without loss of generality that $\mathcal{Z}=\left\{x \in \mathbb{R}^{N}: x_{1}=0\right\}$, we have that $v$ satisfies the assumptions of Proposition 2.7. As a consequence, one can reason once again as in the proof of Proposition 3.1, obtaining a contradiction with the fact that $\gamma<2 s-1$.

Remark 3.11. As we already mentioned in the introduction, in great contrast with the case $s \leq 1 / 2$, if $s>1 / 2$ the fundamental solution of the $s$-laplacian in $\mathbb{R}$ is bounded in a neighborhood of $x=0$. As a consequence, the function $\Gamma(x, y)=\left|\left(x_{1}, y\right)\right|^{2 s-1}$ solves (3.2). This implies that, for $s>1 / 2$, the sets of codimension 1 in $\mathbb{R}^{N}$ have positive $s$-capacity.

## 4. $\mathcal{C}^{0, \alpha}$ UNIFORM BOUNDS

In this section we turn to the proof of the regularity results we stated in the introduction. In particular we will prove Theorem 1.1. We recall that, here and in the following, the functions $f_{i, \beta}$ appearing in problem $(P)_{\beta}^{s}$ are assumed to be continuous and uniformly bounded, with respect to $\beta$, on bounded sets. We start by recalling the regularity results which hold for $\beta$ bounded. For easier notation, we write $B^{+}=B_{1}^{+}$.

Lemma 4.1. There exists $\alpha^{*} \in(0,1)$ such that, for every $\alpha \in\left(0, \alpha^{*}\right), \bar{m}>0$ and $\bar{\beta}>0$, there exists a constant $C=C(\alpha, \bar{m}, \bar{\beta})$ such that

$$
\left\|\mathbf{v}_{\beta}\right\|_{\mathcal{C}^{0, \alpha}}\left(\overline{B_{1 / 2}^{+}}\right) \leq C
$$

for every $\mathbf{v}_{\beta}$ solution of problem $(P)_{\beta}$ on $B^{+}$, satisfying

$$
\beta \leq \bar{\beta} \quad \text { and } \quad\left\|\mathbf{v}_{\beta}\right\|_{L^{\infty}\left(B^{+}\right)} \leq \bar{m} .
$$

Proof. The above regularity issue can be rephrased for a general $h \in H^{1 ; a}\left(B^{+}\right)$ with

$$
\begin{cases}L_{a} h=0 & \text { in } B^{+} \\ h=f \in L^{\infty} & \text { on } \partial^{+} B^{+} \\ \partial_{\nu}^{a} h=g \in L^{\infty} & \text { on } \partial^{0} B^{+} .\end{cases}
$$

Denoting

$$
\tilde{f}(x, y):=f(x,|y|) \quad \text { and } \quad \tilde{g}(x)= \begin{cases}g(x) & x \in \partial^{0} B^{+} \\ 0 & x \in \mathbb{R}^{N} \backslash \partial^{0} B^{+}\end{cases}
$$

we can write $h=h_{1}+h_{2}$, where

$$
\left\{\begin{array} { l l } 
{ L _ { a } h _ { 1 } = 0 } & { \text { in } \mathbb { R } _ { + } ^ { N + 1 } } \\
{ \partial _ { \nu } ^ { a } h _ { 1 } = \tilde { g } } & { \text { on } \mathbb { R } ^ { N } }
\end{array} \text { and } \quad \left\{\begin{array}{ll}
L_{a} h_{2}=0 & \text { in } B \\
h_{2}=\tilde{f}-h_{1} & \text { on } \partial B .
\end{array}\right.\right.
$$

But then the regularity of $h_{1}$ (depending on $\|\tilde{g}\|_{L^{\infty}}$ ) follows by [17, Proposition 2.9], while the one of $h_{2}$ is proved in [12] (see also [5, Section 2]).

From now on, without loss of generality, we will fix $\alpha^{*}>0$ in such a way that Lemma 4.1 holds, and furthermore

$$
\alpha^{*} \leq \begin{cases}\nu^{\mathrm{ACF}} & 0<s \leq \frac{1}{2} \\ \min \left(\nu^{\mathrm{ACF}}, 2 s-1\right) & \frac{1}{2}<s<1\end{cases}
$$

We will obtain Theorem 1.1 for any fixed $\alpha \in\left(0, \alpha^{*}\right)$. Following the outline of [19, Section 6], we proceed by contradiction and develop a blow up analysis. Let $\eta$ denote a smooth function such that

$$
\begin{cases}\eta(X)=1 & 0 \leq|X| \leq \frac{1}{2} \\ 0<\eta(X) \leq 1 & \frac{1}{2} \leq|X| \leq 1 \\ \eta(X)=0 & |X|=1\end{cases}
$$

(in particular, $\eta$ vanishes on $\partial^{+} B^{+}$but is strictly positive $\partial^{0} B^{+}$). We will show that

$$
\|\eta \mathbf{v}\|_{\mathcal{C}^{0, \alpha}\left(\overline{B^{+}}\right)} \leq C
$$

and the theorem will follow by the definition of $\eta$. Let us assume by contradiction the existence of sequences $\left\{\beta_{n}\right\}_{n \in \mathbb{N}},\left\{\mathbf{v}_{n}\right\}_{n \in \mathbb{N}}$, solutions to $(P)_{\beta_{n}}^{s}$, such that

$$
L_{n}:=\max _{i=1, \ldots, k} \max _{X^{\prime} \neq X^{\prime \prime} \in \overline{B^{+}}} \frac{\left|\left(\eta v_{i, n}\right)\left(X^{\prime}\right)-\left(\eta v_{i, n}\right)\left(X^{\prime \prime}\right)\right|}{\left|X^{\prime}-X^{\prime \prime}\right|^{\alpha}} \rightarrow \infty .
$$

By Lemma 4.1 (and the regularity of $\eta$ ) we infer that $\beta_{n} \rightarrow \infty$. Moreover, up to a relabeling, we may assume that $L_{n}$ is achieved by $i=1$ and by two sequences of points $\left(X_{n}^{\prime}, X_{n}^{\prime \prime}\right) \in \overline{B^{+}} \times \overline{B^{+}}$. The first properties of such sequences have already been obtained in [19].

Lemma 4.2 ([19], Lemma 6.4). Let $X_{n}^{\prime} \neq X_{n}^{\prime \prime}$ and $r_{n}:=\left|X_{n}^{\prime}-X_{n}^{\prime \prime}\right|$ satisfy

$$
L_{n}=\frac{\left|\left(\eta v_{1, n}\right)\left(X_{n}^{\prime}\right)-\left(\eta v_{1, n}\right)\left(X_{n}^{\prime \prime}\right)\right|}{r_{n}^{\alpha}} .
$$

Then, as $n \rightarrow \infty$,
(1) $r_{n} \rightarrow 0$;
(2) $\frac{\operatorname{dist}\left(X_{n}^{\prime}, \partial^{+} B^{+}\right)}{r_{n}} \rightarrow \infty, \frac{\operatorname{dist}\left(X_{n}^{\prime \prime}, \partial^{+} B^{+}\right)}{r_{n}} \rightarrow \infty$.

Our analysis is based on two different blow up sequences, one having uniformly bounded Hölder quotient, the other satisfying a suitable problem. Let $\left\{\hat{X}_{n}\right\}_{n \in \mathbb{N}} \subset$ $\overline{B^{+}},\left|\hat{X}_{n}\right|<1$, be a sequence of points, to be chosen later. We write

$$
\tau_{n} B^{+}:=\frac{B^{+}-\hat{X}_{n}}{r_{n}}
$$

remarking that $\tau_{n} B^{+}$is a hemisphere, not necessarily centered on the hyperplane $\{y=0\}$. We introduce the sequences

$$
w_{i, n}(X):=\eta\left(\hat{X}_{n}\right) \frac{v_{i, n}\left(\hat{X}_{n}+r_{n} X\right)}{L_{n} r_{n}^{\alpha}} \quad \text { and } \quad \bar{w}_{i, n}(X):=\frac{\left(\eta v_{i, n}\right)\left(\hat{X}_{n}+r_{n} X\right)}{L_{n} r_{n}^{\alpha}}
$$

where $X \in \tau_{n} B^{+}$. With this choice, on one hand it follows immediately that, for every $i$ and $X^{\prime} \neq X^{\prime \prime} \in \overline{\tau_{n} B^{+}}$,

$$
\frac{\left|\bar{w}_{i, n}\left(X^{\prime}\right)-\bar{w}_{i, n}\left(X^{\prime \prime}\right)\right|}{\left|X^{\prime}-X^{\prime \prime}\right|^{\alpha}} \leq\left|\bar{w}_{1, n}\left(\frac{X_{n}^{\prime}-\hat{X}_{n}}{r_{n}}\right)-\bar{w}_{1, n}\left(\frac{X_{n}^{\prime \prime}-\hat{X}_{n}}{r_{n}}\right)\right|=1
$$

in such a way that the functions $\left\{\overline{\mathbf{w}}_{n}\right\}_{n \in \mathbb{N}}$ share an uniform bound on Hölder seminorm, and at least their first components are not constant. On the other hand, since $\eta\left(\hat{X}_{n}\right)>0$, each $\mathbf{w}_{n}$ solves

$$
\begin{cases}L_{a}^{\tau_{n}} w_{i, n}=0 & \text { in } \tau_{n} B^{+}  \tag{4.1}\\ \partial_{\nu}^{a, \tau_{n}} w_{i, n}=f_{i, n}\left(w_{i, n}\right)-M_{n} w_{i, n} \sum_{j \neq i} a_{i j} w_{j, n}^{2} & \text { on } \tau_{n} \partial^{0} B^{+}\end{cases}
$$

where the new operators write $\left(\hat{X}_{n}=\left(\hat{x}_{n}, \hat{y}_{n}\right)\right)$

$$
L_{a}^{\tau_{n}}=-\operatorname{div}\left(\left(\hat{y}_{n} r_{n}^{-1}+y\right)^{a} \nabla\right), \quad \partial_{\nu}^{a, \tau_{n}}=\lim _{y \rightarrow\left(-\hat{y}_{n} r_{n}^{-1}\right)^{+}}-\left(\hat{y}_{n} r_{n}^{-1}+y\right)^{a} \partial_{y}
$$

and $f_{i, n}(t)=\eta\left(\hat{X}_{n}\right) r_{n}^{2 s-\alpha} L_{n}^{-1} f_{i, \beta_{n}}\left(L_{n} r_{n}^{\alpha} t / \eta\left(\hat{X}_{n}\right)\right), M_{n}=\beta_{n} L_{n}^{2} r_{n}^{2 \alpha+2 s} / \eta\left(\hat{X}_{n}\right)^{2}$.
Remark 4.3. The uniform bound of $\left\|v_{\beta}\right\|_{L^{\infty}}$ imply that

$$
\sup _{\tau_{n} \partial^{0} B^{+}}\left|f_{i, n}\left(w_{i, n}\right)\right|=\eta\left(\hat{X}_{n}\right) r_{n}^{2 s-\alpha} L_{n}^{-1} \sup _{\partial^{0} B^{+}}\left|f_{i, \beta_{n}}\left(v_{i, n}\right)\right| \leq C(\bar{m}) r_{n}^{2 s-\alpha} L_{n}^{-1} \rightarrow 0
$$

as $n \rightarrow \infty$.
A crucial property is that the two blow up sequences defined above have asymptotically equivalent behavior, as enlighten in the following lemma.
Lemma 4.4 ([19], Lemma 6.6). Let $K \subset \mathbb{R}^{N+1}$ be compact. Then
(1) $\max _{X \in K \cap \overline{\tau_{n} B^{+}}}\left|\mathbf{w}_{n}(X)-\overline{\mathbf{w}}_{n}(X)\right| \rightarrow 0$;
(2) there exists $C$, only depending on $K$, such that $\left|\mathbf{w}_{n}(X)-\mathbf{w}_{n}(0)\right| \leq C$, for every $x \in K$.

Now we show that the sequences $\left(X_{n}^{\prime}, X_{n}^{\prime \prime}\right)$ accumulates towards $\{y=0\}$.
Lemma 4.5. There exists $C>0$ such that, for every $n$ sufficiently large,

$$
\frac{\operatorname{dist}\left(X_{n}^{\prime}, \partial^{0} B^{+}\right)+\operatorname{dist}\left(X_{n}^{\prime \prime}, \partial^{0} B^{+}\right)}{r_{n}} \leq C
$$

Proof. We argue by contradiction. Taking into account the second part of Lemma 4.2, this forces

$$
\frac{\operatorname{dist}\left(X_{n}^{\prime}, \partial B^{+}\right)+\operatorname{dist}\left(X_{n}^{\prime \prime}, \partial B^{+}\right)}{r_{n}} \rightarrow \infty
$$

In the definition of $\mathbf{w}_{n}, \overline{\mathbf{w}}_{n}$ we choose $\hat{X}_{n}=X_{n}^{\prime}$, so that $\tau_{n} B^{+} \rightarrow \mathbb{R}^{N+1}$ and $\hat{y}_{n}^{-1} r_{n} \rightarrow 0$. Let $K$ be any fixed compact set. Then, by definition, $K$ is contained in the half sphere $\tau_{n} B^{+}$, for every $n$ sufficiently large. By defining $\mathbf{W}_{n}=\mathbf{w}_{n}-\mathbf{w}_{n}(0)$, $\overline{\mathbf{W}}_{n}=\overline{\mathbf{w}}_{n}-\overline{\mathbf{w}}_{n}(0)$, we obtain that $\left\{\overline{\mathbf{W}}_{n}\right\}_{n \in \mathbb{N}}$ is a sequence of functions which share the same $\mathcal{C}^{0, \alpha^{2}}$-seminorm and are uniformly bounded in $K$, since $\overline{\mathbf{W}}_{n}(0)=0$. By the Ascoli-Arzelà Theorem, there exists a function $\mathbf{W} \in C(K)$ which, up to a subsequence, is the uniform limit of $\left\{\overline{\mathbf{W}}_{n}\right\}_{n \in \mathbb{N}}$ : taking a countable compact exhaustion of $\mathbb{R}^{N+1}$ we find that $\overline{\mathbf{W}}_{n} \rightarrow \mathbf{W}$ uniformly in every compact set. Moreover, for any pair $X, Y$, we have that $X, Y \in \tau_{n} B^{+}$for every $n$ sufficiently large, and so

$$
\left|\overline{\mathbf{W}}_{n}(X)-\overline{\mathbf{W}}_{n}(Y)\right| \leq \sqrt{k}|X-Y|^{\alpha}
$$

Passing to the limit in $n$ the previous expression, we obtain $\mathbf{W} \in \mathcal{C}^{0, \alpha}\left(\mathbb{R}^{N+1}\right)$. By Lemma 4.4, we also find that $\mathbf{W}_{n} \rightarrow \mathbf{W}$ uniformly on compact sets. We want to show that $\mathbf{W}$ is harmonic. To this purpose, let $\varphi \in \mathcal{C}_{0}^{\infty}\left(\mathbb{R}^{N+1}\right)$ be a smooth test function, and let $\bar{n}$ be sufficiently large so that $\operatorname{supp} \varphi \subset \tau_{n} B^{+}$for all $n \geq \bar{n}$. For a fixed $i \in\{1, \ldots, k\}$, we test the equation $L_{a}^{\tau_{n}} w_{i, n}=0$ by $\varphi$ to find

$$
\int_{\mathbb{R}^{N+1}}-\operatorname{div}\left(\left(1+y r_{n} \hat{y}_{n}^{-1}\right)^{a} \nabla \varphi\right) w_{i, n} \mathrm{~d} x \mathrm{~d} y=0
$$

Passing to the uniform limit and observing that $\left(1+y r_{n} \hat{y}_{n}^{-1}\right)^{a} \rightarrow 1$ in $\mathcal{C}^{\infty}(\operatorname{supp} \varphi)$, we obtain at once that $\mathbf{W}$ is indeed harmonic. We will obtain a contradiction with the classical Liouville Theorem once we show that $\mathbf{W}$ is not constant. To this aim we observe that $\left(X_{n}^{\prime}-\hat{X}_{n}\right) / r_{n}=0$ and, up to a subsequence,

$$
\frac{X_{n}^{\prime \prime}-\hat{X}_{n}}{r_{n}}=\frac{X_{n}^{\prime \prime}-X_{n}^{\prime}}{\left|X_{n}^{\prime \prime}-X_{n}^{\prime}\right|} \rightarrow X^{\prime \prime} \in \partial B_{1} .
$$

Therefore, by equicontinuity and uniform convergence,

$$
\left|\bar{W}_{1, n}\left(\frac{X_{n}^{\prime}-\hat{X}_{n}}{r_{n}}\right)-\bar{W}_{1, n}\left(\frac{X_{n}^{\prime \prime}-\hat{X}_{n}}{r_{n}}\right)\right|=1 \Longrightarrow\left|W_{1}(0)-W_{1}\left(X^{\prime \prime}\right)\right|=1
$$

After the result above, we are in a position to choose $\hat{X}_{n}$ in the definition of $\mathbf{w}_{n}$, $\overline{\mathbf{w}}_{n}$ as

$$
\hat{X}_{n}:=\left(x_{n}^{\prime}, 0\right),
$$

where as usual $X_{n}^{\prime}=\left(x_{n}^{\prime}, y_{n}^{\prime}\right)$. With this choice, it is immediate to see that

$$
L_{a}^{\tau_{n}}=L_{a}, \quad \partial_{\nu}^{a, \tau_{n}}=\partial_{\nu}^{a}, \quad \tau_{n} B^{+} \rightarrow \Omega_{\infty}=\mathbb{R}_{+}^{N+1}
$$

Moreover, by Lemma 4.5, we have that $X_{n}^{\prime}, X_{n}^{\prime \prime} \in B_{C}^{+}$, for some $C$ not depending on $n$. This will imply that any possible blow up limit can not be constant. Now one can reason as in $[19$, Section 6] in order to prove that the blow up sequences converge. In doing this, a first crucial step consists in proving that $\mathbf{w}_{n}(0)$ is bounded: to this aim, it is useful to notice that the decay rate for subsolutions which we obtained in Lemma 3.5 does not depend on $s$ and completely agrees with the one found in [19, Lemma 4.5]. Consequently, the uniform bound on the Hölder seminorm allows to prove the following result.

Lemma 4.6 ([19], Lemma 6.13). Under the previous blow up setting, there exists $\mathbf{w} \in\left(H_{\mathrm{loc}}^{1 ; a} \cap \mathcal{C}^{0, \alpha}\right)\left(\overline{\mathbb{R}_{+}^{N+1}}\right)$ such that, up to a subsequence,

$$
\mathbf{w}_{n} \rightarrow \mathbf{w} \text { in }\left(H^{1} \cap C\right)(K)
$$

for every compact $K \subset \overline{\mathbb{R}_{+}^{N+1}}$.
End of the proof of Theorem 1.1. Up to now, we have that $\mathbf{w}_{n} \rightarrow \mathbf{w}$ in $\left(H^{1 ; a} \cap\right.$ $C)_{\text {loc }}$, and that the limiting blow up profile $\mathbf{w}$ is a nonconstant vector of harmonic, globally Hölder continuous functions. To reach the final contradiction, we distinguish, up to subsequences, between the following three cases.

Case 1: $M_{n} \rightarrow 0$. In this case also the equation on the boundary passes to the limit, and the nonconstant component $w_{1}$ satisfies $\partial_{\nu}^{a} w_{1} \equiv 0$ on $\mathbb{R}^{N}$, in contradiction with Corollary 3.3.

Case 2: $M_{n} \rightarrow C>0$. Even in this case the equation on the boundary passes to the limit, and $\mathbf{w}$ solves

$$
\begin{cases}L_{a} w_{i}=0 & x \in \mathbb{R}_{+}^{N+1} \\ \partial_{\nu}^{a} w_{i}=-C w_{i} \sum_{j \neq i} a_{i j} w_{j}^{2} & \text { on } \mathbb{R}^{N} \times\{0\}\end{cases}
$$

The contradiction is now reached using Proposition 3.9.
Case 3: $M_{n} \rightarrow \infty$. In this case we can find a contradiction with Proposition 3.10. To this aim, one has to prove the validity of a Pohozaev-type identity for the limits of the blow-up sequences. This can be done by taking into account Lemma 4.6 and reasoning as in [19, Section 5].

As of now, the contradictions we have obtained imply that $\left\{\mathbf{v}_{\beta}\right\}_{\beta>0}$ is uniformly bounded in $\mathcal{C}^{0, \alpha}\left(\overline{B_{1 / 2}^{+}}\right)$, for every $\alpha<\alpha^{*}$. But then the relative compactness in $\mathcal{C}^{0, \alpha}\left(\overline{B_{1 / 2}^{+}}\right)$follows by Ascoli-Arzelà Theorem, while the one in $H^{1 ; a}\left(B_{1 / 2}^{+}\right)$can be shown by reasoning as in the proof of Lemma 4.6.

Incidentally, we remark that similar arguments can be exploited in order to prove the following compactness result, concerning segregated profiles (see also [19, Proposition 6.15]). This result, though technical at this stage, provides a compactness criterion for suitable blow down sequences, and may be useful in proving optimal regularity results, along the scheme explained in the introduction.

Proposition 4.7. Let $\left\{\mathbf{v}_{n}\right\}_{n \in \mathbb{N}}$ be a subset of $\mathcal{C}^{0, \alpha}\left(\overline{B_{1}^{+}}\right)$, for some $0<\alpha \leq \alpha^{*}$, and satisfy the assumptions of Proposition 2.11. If

$$
\left\|\mathbf{v}_{n}\right\|_{L^{\infty}\left(B_{1}^{+}\right)} \leq \bar{m}
$$

with $\bar{m}$ independent of $n$, then for every $\alpha^{\prime} \in(0, \alpha)$ there exists a constant $C=$ $C\left(\bar{m}, \alpha^{\prime}\right)$, not depending on $n$, such that

$$
\left\|\mathbf{v}_{n}\right\|_{\mathcal{C}^{0, \alpha^{\prime}}}\left(\overline{B_{1 / 2}^{+}}\right) \leq C .
$$

Furthermore, $\left\{\mathbf{v}_{n}\right\}_{n \in \mathbb{N}}$ is relatively compact in $H^{1 ; a}\left(B_{1 / 2}^{+}\right) \cap \mathcal{C}^{0, \alpha^{\prime}}\left(\overline{B_{1 / 2}^{+}}\right)$for every $\alpha^{\prime}<\alpha$.

To conclude, we mention that the above local result can be used, together with a covering argument and Proposition 3.4, to prove Theorem 1.2 (see also [19, Theorem $8.5]$ ): there are, however, two different situations to be handled.

First, if one considers the problem (1.1) set on the whole $\mathbb{R}^{N}$ (Theorem 1.2 in the case $\Omega=\mathbb{R}^{N}$ ), then the global uniform bounds on $\mathbf{u}_{\beta}$ imply, by the representation formula of Caffarelli and Silvestre [6], that also $\mathbf{v}_{\beta}$ enjoy the same uniform $L^{\infty}$ bounds. As a consequence, the local uniform bounds extend at once to the global case by a simple covering argument.

In the case of $\Omega \neq \mathbb{R}^{N}$, one has to deal also with the boundary of $\Omega$. In this situation, the regularity for $\mathbf{u}_{\beta}$ is ensured by [16], while the uniform Hölder bounds - obtained again via the blow up analysis - follows with similar arguments and the use of the appropriate Liouville type results (Proposition 3.4). Further details can be found in [19, Section 8].

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