$$
J(u+h)-J(u)=\int_{\Omega}\left\langle\nabla_{\mathbb{G}} u, \nabla_{\mathbb{G}} h\right\rangle \mathrm{d} x+J(h)
$$

for every $h \in C_{0}^{\infty}(\Omega, \mathbb{R})$. We call critical point of $J$ any function $u \in$ $C^{\infty}(\Omega, \mathbb{R})$ such that

$$
\int_{\Omega}\left\langle\nabla_{\mathbb{G}} u, \nabla_{\mathbb{G}} h\right\rangle \mathrm{d} x, \quad \forall h \in C_{0}^{\infty}(\Omega, \mathbb{R}) .
$$

Then, given $u \in C^{\infty}(\Omega, \mathbb{R})$, we have: $u$ is a critical point of $J$ if and only if $\Delta_{\mathbb{G}} u=0$ in $\Omega$. Indeed, since $Z_{j}^{*}=-Z_{j}$, an integration by parts gives

$$
\begin{aligned}
\int_{\Omega}\left\langle\nabla_{\mathbb{G}} u, \nabla_{\mathbb{G}} h\right\rangle \mathrm{d} x & =\sum_{j=1}^{N_{1}} \int_{\Omega} Z_{j} u Z_{j} h \mathrm{~d} x=-\sum_{j=1}^{N_{1}} \int_{\Omega}\left(Z_{j}^{2} u\right) h \mathrm{~d} x \\
& =-\int_{\Omega}\left(\Delta_{\mathbb{G}} u\right) h \mathrm{~d} x
\end{aligned}
$$

for every $u \in C^{\infty}(\Omega, \mathbb{R})$ and $h \in C_{0}^{\infty}(\Omega, \mathbb{R})$.
We end this section with the following remarkable result.
Proposition 1.4.6. Let $\Omega$ be an open connected subset of the Carnot group $\mathbb{G}$. Then a function $u \in C^{1}(\Omega, \mathbb{R})$ is constant in $\Omega$ if and only if its canonical intrinsic gradient $\nabla_{\mathbb{G}} u$ vanishes identically on $\Omega$.

Proof. Suppose $Z_{1} u, \ldots, Z_{N_{1}} u$ vanish identically on $\Omega$. Since the Lie algebra of $\mathbb{G}$ is given by Lie $\left\{Z_{1}, \ldots Z_{N_{1}}\right\}$ (see (1.46)), then for every vector field $Z_{j}$ of the Jacobian basis, we have $Z_{j} u \equiv 0$. We end by applying Proposition 1.2.13.

### 1.5 Examples

### 1.5.1 Euclidean group

The additive group $\left(\mathbb{R}^{N},+\right)$ is a homogeneous group with respect to the dilations

$$
\delta_{\lambda}(x)=\lambda x, \quad \lambda>0
$$

We call $\mathbb{E}=\left(\mathbb{R}^{N},+, \delta_{\lambda}\right)$ the Euclidean group. $\mathbb{E}$ is a Carnot group of step 1 . Its generators are $\partial_{x_{1}}, \ldots, \partial_{x_{N}}$. Thus, the canonical sub-Laplacian on $\mathbb{E}$ is the classical Laplace operator

$$
\Delta=\sum_{j=1}^{N} \partial_{x_{j}}^{2}
$$

We want to stress that $\mathbb{E}$ is the only Carnot group of step 1 and $N$ generators.

### 1.5.2 Heisenberg-Weyl group

Let us consider in $\mathbb{R}^{2 n+1}$ the following composition law

$$
\begin{equation*}
(z, t) \circ\left(z^{\prime}, t^{\prime}\right)=\left(z+z^{\prime}, t+t^{\prime}+2 \operatorname{Im}\left(z \cdot \overline{z^{\prime}}\right)\right) \tag{1.59}
\end{equation*}
$$

Hereafter we agree to identify $\mathbb{R}^{2 n}$ with $\mathbb{C}^{n}$ and to use the following notation to denote the point of $\mathbb{R}^{2 n+1} \equiv \mathbb{C}^{n} \times \mathbb{R}$ :

$$
(z, t)=(x, y, t)=\left(x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}, t\right)
$$

with $x_{j}, y_{j}, t \in \mathbb{R}, z_{j}=x_{j}+i y_{j}, z=\left(z_{1}, \ldots, z_{n}\right)$. In (1.59), $z \cdot \overline{z^{\prime}}$ denotes the usual hermitian inner product in $\mathbb{C}^{n}$, i.e., $z \cdot \overline{z^{\prime}}=\sum_{j=1}^{n}\left(x_{j}+i y_{j}\right)\left(x_{j}^{\prime}-i y_{j}^{\prime}\right)$. Then, the composition law o can be written as

$$
(z, t) \circ\left(z^{\prime}, t^{\prime}\right)=\left(x+x^{\prime}, y+y^{\prime}, t+t^{\prime}+2\left(y x^{\prime}-x y^{\prime}\right)\right)
$$

It is quite easy to verify that $\left(\mathbb{R}^{2 n+1}, o\right)$ is a Lie group whose zero is the origin and where the inverse is given by $(z, t)^{-1}=(-z,-t)$. Let us now consider the dilations

$$
\delta_{\lambda}: \mathbb{R}^{2 n+1} \rightarrow \mathbb{R}^{2 n+1}, \quad \delta_{\lambda}(z, t)=\left(\lambda z, \lambda^{2} t\right)
$$

A trivial computation shows that $\delta_{\lambda}$ is an automorphism of $\left(\mathbb{R}^{2 n+1}, \circ\right)$ for every $\lambda>0$. Then $\mathbb{H}^{n}=\left(\mathbb{R}^{2 n+1}, \circ, \delta_{\lambda}\right)$ is a homogeneous group. It is called the Heisenberg-Weyl group in $\mathbb{R}^{2 n+1}$.

The Jacobian matrix at the origin of the left translation $\tau_{(z, t)}$ is the following block matrix

$$
\mathcal{J}_{\tau_{(z, t)}}(0,0)=\left(\begin{array}{ccc}
\mathbb{I}_{n} & 0 & 0 \\
0 & \mathbb{I}_{n} & 0 \\
2 y & -2 x & 1
\end{array}\right)
$$

where $\mathbb{I}_{n}$ denote the $n \times n$ identity matrix, while $2 y$ and $-2 x$ stand for the $1 \times n$ matrices $\left(2 y_{1}, \ldots, 2 y_{n}\right)$ and $\left(-2 x_{1}, \ldots,-2 x_{n}\right)$, respectively. Then, the Jacobian basis of $\mathfrak{h}_{n}$, the Lie algebra of $\mathbb{H}^{n}$, is given by

$$
X_{j}=\partial_{x_{j}}+2 y_{j} \partial_{t}, \quad Y_{j}=\partial_{y_{j}}-2 x_{j} \partial_{t}, \quad j=1, \ldots, n, \quad T=\partial_{t}
$$

Then, since $\left[X_{j}, Y_{j}\right]=-\frac{1}{4} \partial_{t}$, we have

$$
\begin{aligned}
& \operatorname{rank}\left(\operatorname{Lie}\left\{X_{1}, \ldots, X_{n}, Y_{1}, \ldots, Y_{n}\right\}(0,0)\right) \\
& \quad=\operatorname{dim}\left(\operatorname{span}\left\{\partial_{x_{1}}, \ldots, \partial_{x_{n}}, \partial_{y_{1}}, \ldots, \partial_{y_{n}}, \partial_{t}\right\}\right)=2 n+1
\end{aligned}
$$

This shows that $\mathbb{H}^{n}$ is a Carnot group. Its step is $r=2$ and its generators are the vector fields $X_{j}, Y_{j}, j=1, \ldots, n$. As a consequence, the canonical sub-Laplacian on $\mathbb{H}^{n}$ is given

$$
\Delta_{\mathbb{H}^{n}}=\sum_{j=1}^{n}\left(X_{j}^{2}+Y_{j}^{2}\right)
$$

### 1.5.3 B-groups

Let us consider a $N \times N$ matrix $B$ with real entries $b_{i, j}, i, j=1, \ldots, N$. Let us put

$$
E(t):=\exp (t B), \quad t \in \mathbb{R}
$$

In $\mathbb{R}^{1+N}$, whose point will be denoted by $z=(t, x), t \in \mathbb{R}, x \in \mathbb{R}^{N}$, let us introduce the following composition law

$$
(t, x) \circ\left(t^{\prime}, x^{\prime}\right)=\left(t+t^{\prime}, x^{\prime}+E\left(t^{\prime}\right) x\right) .
$$

One easily verifies that $\mathbb{B}=\left(\mathbb{R}^{1+N}, \circ\right)$ is a Lie group whose zero is the origin $(0,0)$ and where the inverse is given by

$$
(t, x)^{-1}=(-t,-E(-t) x)
$$

The Jacobian matrix at the origin of the left translation $\tau_{(t, x)}$ is the following block matrix

$$
\mathcal{J}_{(t, x)}(0,0)=\left(\begin{array}{ll}
1 & 0 \\
b \mathbb{I}_{N}
\end{array}\right)
$$

where $b$ stands for the $N \times 1$ matrix

$$
\left.\frac{\mathrm{d}}{\mathrm{~d} s}\right|_{s=0} E(s) x=\left.B E(s) x\right|_{s=0}=B x
$$

Then, the Jacobian basis of $\mathfrak{b}$, the Lie algebra of $\mathbb{B}$, is given by

$$
\begin{equation*}
Y=\partial_{t}+\nabla_{x} \cdot B x, \quad \partial_{x_{1}}, \ldots, \partial_{x_{N}} \tag{1.60}
\end{equation*}
$$

We explicitly remark that, for a general matrix $B$, the group ( $\mathbb{B}, \circ$ ) may not be nilpotent. Indeed, an easy computation shows that, for any $j \in\{1, \ldots, N\}$

$$
[\underbrace{\partial_{x_{j}},\left[\partial_{x_{j}}, \cdots\left[\partial_{x_{j}}\right.\right.}_{k \text { times }}, Y] \cdots]]=\sum_{i=1}^{N}\left(B^{k}\right)_{i, j} \partial_{x_{i}}
$$

Hence, $(\mathbb{B}, \circ)$ is a nilpotent group iff $B$ is a nilpotent matrix. For example, if $N=1$ and $B=(1)$, the composition law is

$$
(t, x) \circ\left(t^{\prime}, x^{\prime}\right)=\left(t+t^{\prime}, x^{\prime}+e^{t^{\prime}} x\right), \quad(t, x),\left(t^{\prime}, x^{\prime}\right) \in \mathbb{R}^{2}
$$

and the Jacobian basis is $\partial_{t}+x \partial_{x}, \partial_{x} . \mathbb{R}^{2}$ equipped with the above composition law is not a Carnot group (and it is not even diffeomorphic to any Carnot group) since it is not nilpotent. In particular, the second order differential operator on $\mathbb{R}^{2}$ defined by

$$
L=\partial_{x}^{2}+\left(\partial_{t}+x \partial_{x}\right)^{2}=\left(1+x^{2}\right) \partial_{x}^{2}+\partial_{t}^{2}+2 x \partial_{x} \partial_{t}+x \partial_{x}
$$

is a sum of squares of left-invariant vector fields on ( $\mathbb{R}^{2}, \circ$ ), it satisfies Hörmander's ipoellipticity condition

$$
\operatorname{rank}\left(\operatorname{Lie}\left\{\partial_{x}, \partial_{t}+x \partial_{x}\right\}(t, x)\right)=2, \quad \forall(t, x) \in \mathbb{R}^{2}
$$

but $L$ is not a sub-Laplacian on any Carnot group. Indeed, $L$ is elliptic at any point.

### 1.5.4 K-type groups

Let us now suppose that the matrix $B$ in the previous example takes the following special form

$$
\left(\begin{array}{ccccc}
0 & 0 & \cdots & 0 & 0  \tag{1.61}\\
B_{1} & 0 & \cdots & 0 & 0 \\
0 & B_{2} & \ddots & \vdots & \vdots \\
\vdots & \vdots & \ddots & 0 & 0 \\
0 & 0 & \cdots & B_{r} & 0
\end{array}\right)
$$

where $B_{j}$ is a $p_{j} \times p_{j-1}$ block with rank $p_{j}, j=1,2, \ldots, r$. Moreover $p_{0} \geq p_{1} \geq$ $\cdots \geq p_{r}$ and $p_{0}+p_{1}+\cdots+p_{r}=N$. We want to show that the group $\mathbb{B}$ related to this matrix is a Carnot group. It will be called a group of Kolmogorov type or, in short, a K-type group.

Let us split $\mathbb{R}^{N}$ as follows

$$
\mathbb{R}^{N}=\mathbb{R}^{p_{0}} \times \cdots \times \mathbb{R}^{p_{r}}
$$

and define, for every $\lambda>0$,

$$
\begin{equation*}
D_{\lambda} x=D_{\lambda}\left(x^{(0)}, \ldots, x^{(r)}\right)=\left(\lambda x^{(0)}, \ldots, \lambda^{r+1} x^{(r)}\right) \tag{1.62}
\end{equation*}
$$

where $x^{(i)} \in \mathbb{R}^{p_{i}}$ for $0 \leq i \leq r$. We also put $\delta_{\lambda}(t, x)=\left(\lambda t, D_{\lambda} x\right)$.
Claim 1 For every $\lambda>0$, the dilation $\delta_{\lambda}$ is an automorphism of $\mathbb{B}$.
To prove this claim we need the following lemma.
Lemma 1.5.1. For every $t \in \mathbb{R}$ and $\lambda>0$, we have

$$
\begin{equation*}
E(\lambda t) D_{\lambda}=D_{\lambda} E(t) \tag{1.63}
\end{equation*}
$$

where $E(t)=\exp (t B), B$ is as in (1.61) and $D_{\lambda}$ is the dilation in (1.62).
Proof. Since $B^{k}=0$ for every $k \geq r+1$, one has $E(t)=\sum_{k=0}^{r} t^{k} B^{k} / k!$ and (1.63) holds for every $t \in \mathbb{R}$ and $\lambda>0$ iff

$$
\begin{equation*}
\lambda^{k} B^{k} D_{\lambda}=D_{\lambda} B^{k}, \quad \forall k \geq 0, \quad \forall \lambda>0 \tag{1.64}
\end{equation*}
$$

This identity holds true when $k=0$. An easy direct computation shows that it also holds true for $k=1$. As a consequence

$$
\lambda^{2} B^{2} D_{\lambda}=\lambda B\left(\lambda B D_{\lambda}\right)=\lambda B\left(D_{\lambda} B\right)=\left(\lambda B D_{\lambda}\right) B=\left(D_{\lambda} B\right) B=D_{\lambda} B^{2}
$$

Then (1.64) holds true for $k=2$. An iteration of this argument shows (1.64) for $k \geq 2$.

From this lemma, the Claim 1 easily follows. Indeed, for every $z=(t, x)$, $z^{\prime}=\left(t^{\prime}, x^{\prime}\right) \in \mathbb{R}^{1+N}$ we have

$$
\left(\delta_{\lambda} z\right) \circ\left(\delta_{\lambda} z^{\prime}\right)=\left(\lambda t, D_{\lambda} x\right) \circ\left(\lambda t^{\prime}, D_{\lambda} x^{\prime}\right)=\left(\lambda t+\lambda t^{\prime}, D_{\lambda} x^{\prime}+E\left(\lambda t^{\prime}\right) D_{\lambda} x\right)
$$

$($ by Lemma 1.5.1 $)=\left(\lambda\left(t+t^{\prime}\right), D_{\lambda} x^{\prime}+D_{\lambda} E\left(t^{\prime}\right) x\right)=\delta_{\lambda}\left(t+t^{\prime}, x^{\prime}+E\left(t^{\prime}\right) x\right)$

$$
=\delta_{\lambda}\left(z \circ z^{\prime}\right)
$$

Thus $\mathbb{B}=\left(\mathbb{R}^{1+N}, \circ, \delta_{\lambda}\right)$ is a homogeneous group whose first layer is $\mathbb{R} \times$ $\mathbb{R}^{p_{0}}=\left\{\left(t, x^{(0)}\right) \mid t \in \mathbb{R}, x^{(0)} \in \mathbb{R}^{p_{0}}\right\}$. Moreover, the vector fields in the Jacobian basis related to this first layer are given by

$$
\begin{equation*}
Y=\partial_{t}+\left\langle B x, \nabla_{x}\right\rangle, \quad \partial_{x_{1}}, \ldots, \partial_{x_{p_{0}}} \tag{1.65}
\end{equation*}
$$

Claim 2 We have $\operatorname{rank}\left(\operatorname{Lie}\left\{Y, \partial_{x_{1}}, \ldots, \partial_{x_{p_{0}}}\right\}(0,0)\right)=1+N$.
Once this claim is proved, it will follow that $\left(\mathbb{R}^{1+N}, \circ, \delta_{\lambda}\right)$ is a Carnot group of step $r+1$ and generators the $1+p_{0}$ vector fields in (1.65). Thus the related canonical sub-Laplacian is given by

$$
\begin{equation*}
\Delta_{\mathbb{B}}=Y^{2}+\Delta_{\mathbb{R}^{p_{0}}}, \quad \Delta_{\mathbb{R}^{p_{0}}}=\sum_{j=1}^{p_{0}} \partial_{x_{j}}^{2} \tag{1.66}
\end{equation*}
$$

This sub-Laplacian will be said of Kolmogorov type. To prove Claim 2, the following lemma will be useful.

Lemma 1.5.2. In $\mathbb{R}^{p} \times \mathbb{R}^{q}$ let us consider the vector field

$$
Z=A y \cdot\left(\nabla_{z}\right)^{T}, \text { where } A \text { is a } q \times p \text { matrix, } y \in \mathbb{R}^{p} \text { and } z \in \mathbb{R}^{q}
$$

Suppose $\operatorname{rank}(A)=q \leq p$. Then

$$
\begin{equation*}
\operatorname{span}\left\{\left[\partial_{y_{i}}, Z\right] \mid i=1, \ldots, p\right\}=\operatorname{span}\left\{\partial_{z_{1}}, \ldots, \partial_{z_{q}}\right\} \tag{1.67}
\end{equation*}
$$

Proof. Let $A=\left(a_{i, j}\right)_{i \leq q, j \leq p}$. Then

$$
\left[\partial_{y_{i}}, Z\right]=\sum_{j=1}^{q} a_{j, i} \partial_{z_{j}}, \quad i=1, \ldots, p
$$

so that, $\operatorname{since} \operatorname{rank}(A)=q$,

$$
\operatorname{dim}\left(\operatorname{span}\left\{\left[\partial_{y_{i}}, Z\right] \mid i=1, \ldots, p\right\}\right)=q
$$

This implies (1.67).
We now prove Claim 2. Since $B$ has the form (1.61), we can write

$$
Y=\partial_{t}+\sum_{i=1}^{r} B_{i} x^{(i-1)} \cdot\left(\nabla_{x^{(i)}}\right)^{T}
$$

Then, by applying Lemma 1.5.2, we get

$$
\begin{aligned}
\operatorname{span}\left\{\left[\partial_{x_{i}}, Y\right] \mid i=1, \ldots, p_{0}\right\} & =\operatorname{span}\left\{\left[\partial_{x_{i}}, B_{1} x^{(0)} \cdot\left(\nabla_{x^{(1)}}\right)^{T}\right] \mid i=1, \ldots, p_{0}\right\} \\
& =\operatorname{span}\left\{\partial_{x_{i}^{(1)}} \mid i=1, \ldots, p_{1}\right\} .
\end{aligned}
$$

Another application of Lemma 1.5.2 gives

$$
\operatorname{span}\left\{\left[\partial_{x_{i}^{(1)}}, Y\right] \mid i=1, \ldots, p_{1}\right\}=\operatorname{span}\left\{\partial_{x_{i}^{(2)}} \mid i=1, \ldots, p_{2}\right\}
$$

Iterating this argument, we get

$$
\operatorname{Lie}\left\{Y, \partial_{x_{1}}, \ldots, \partial_{x_{p_{0}}}\right\}=\operatorname{Lie}\left\{Y, \partial_{x_{1}}, \ldots, \partial_{x_{N}}\right\}
$$

This obviously shows the claim.
The groups of Kolmogorov type were introduced in [32] in studying a class of hypoelliptic ultraparabolic operators including the classical prototype operators of Kolmogorov-Fokker-Planck. The composition law in [32] was suggested by the structure of the fundamental solution of the operator in $\mathbb{R}^{3}$ $\partial_{x_{1}}^{2}+x_{1} \partial_{x_{2}}-\partial_{x_{3}}$ given by Kolmogorov in [31].
Remark 1.5.3. Assume that the matrix $B$ is as in (1.61). If we define

$$
\begin{aligned}
& d_{\lambda}: \mathbb{R}^{1+N} \rightarrow \mathbb{R}^{1+N} \\
& d_{\lambda}\left(t, x^{(0)}, \ldots, x^{(r)}\right)=\left(\lambda^{2} t, \lambda x^{(0)}, \lambda^{3} x^{(1)}, \ldots, \lambda^{2 r+1} x^{(r)}\right),
\end{aligned}
$$

then $\left\{d_{\lambda}\right\}_{\lambda>0}$ is a group of automorphisms of $\mathbb{B}$. For a proof of this statement, we directly refer to [32]. This remark shows that $\left(\mathbb{R}^{1+N}, \circ, d_{\lambda}\right)$ is a homogeneous Lie group. It can be also easily be proved that the ultraparabolic operator

$$
\begin{equation*}
L=\Delta_{p_{0}}+Y \tag{1.68}
\end{equation*}
$$

is left-translation invariant and homogeneous of degree two with respect to $\left\{d_{\lambda}\right\}_{\lambda>0}$. Operator (1.68) generalizes the prototypes of the ones introduced by Kolmogorov in [31].

### 1.5.5 Homogeneous groups of step two

Let $\mathbb{R}^{N}$ be split as $\mathbb{R}^{N}=\mathbb{R}^{m} \times \mathbb{R}^{n}$ and denote its point by $z=(x, t)$ with $x \in \mathbb{R}^{m}$ and $t \in \mathbb{R}^{n}$. Given an $n$-tuple $B^{(1)}, \ldots, B^{(n)}$ of $m \times m$ matrices with real entries, let

$$
\begin{equation*}
(x, t) \circ(\xi, \tau)=\left(x+\xi, t+\tau+\frac{1}{2}\langle B x, \xi\rangle\right) . \tag{1.69}
\end{equation*}
$$

Here $\langle B x, \xi\rangle$ denotes the $n$-tuple $\left(\left\langle B^{(1)} x, \xi\right\rangle, \ldots\left\langle B^{(n)} x, \xi\right\rangle\right)$ and $\langle$,$\rangle stands for$ the inner product in $\mathbb{R}^{m}$. One can easily verify that $\left(\mathbb{R}^{N}, o\right)$ is a Lie group whose identity is the origin and where the inverse is given by $(x, t)^{-1}=$ $(-x,-t+\langle B x, x\rangle)$. It is also quite easy to recognize that the dilation

$$
\begin{equation*}
\delta_{\lambda}: \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}, \quad \delta_{\lambda}(x, t)=\left(\lambda x, \lambda^{2} t\right) \tag{1.70}
\end{equation*}
$$

is an automorphism of $\left(\mathbb{R}^{N}, \circ\right)$, for any $\lambda>0$. Then $\mathbb{G}=\left(\mathbb{R}^{N}, \circ, \delta_{\lambda}\right)$ is a homogeneous group.

We explicitly remark that the composition law of any Lie group in $\mathbb{R}^{m} \times \mathbb{R}^{n}$, homogeneous w.r.t. the dilations $\left\{\delta_{\lambda}\right\}_{\lambda}$ as in (1.70), takes the form (1.69), see Theorem 1.3.11.

The Jacobian matrix at $(0,0)$ of the left translation $\tau_{(x, t)}$ takes the following block form

$$
\mathcal{J}_{\tau_{(x, t)}}(0,0)=\left(\begin{array}{cc}
\mathbb{I}_{m} & 0 \\
\frac{1}{2} B x \mathbb{I}_{n}
\end{array}\right)
$$

where if $B^{(k)}=\left(b_{i, j}^{(k)}\right)_{i, j \leq m}$, for $k=1, \ldots, n, B x$ denotes the matrix

$$
\left(\sum_{j=1}^{m} b_{i, j}^{(k)} x_{j}\right)_{k \leq m, j \leq n}
$$

Then, the Jacobian basis of $\mathfrak{g}$, the Lie algebra of $\mathbb{G}$, is given by

$$
\begin{align*}
& X_{i}=\left(\partial / \partial x_{i}\right)+\frac{1}{2} \sum_{k=1}^{n}\left(\sum_{l=1}^{m} b_{i, l}^{(k)} x_{l}\right)\left(\partial / \partial t_{k}\right), \quad(i=1, \ldots, m)  \tag{1.71}\\
& T_{k}=\partial / \partial t_{k}, \quad(k=1, \ldots, n)
\end{align*}
$$

An easy computation shows that

$$
\left[X_{j}, X_{i}\right]=\sum_{k=1}^{n} \frac{1}{2}\left(b_{i, j}^{(k)}-b_{j, i}^{(k)}\right) \partial_{t_{k}}=: \sum_{k=1}^{n} c_{i, j}^{(k)} \partial_{t_{k}}
$$

We have denoted by $C^{(k)}=\left(c_{i, j}^{(k)}\right)_{i, j \leq m}$ the skew-symmetric part of $B^{(k)}$. Let us now assume that $C^{(1)}, \ldots, C^{(n)}$ are linearly independent. This implies that the $m^{2} \times n$ matrix

$$
\left(\begin{array}{ccc}
C_{1,1}^{(1)} & \cdots & C_{1,1}^{(n)} \\
\vdots & \cdots & \vdots \\
C_{m, m}^{(1)} & \cdots & C_{m, m}^{(n)}
\end{array}\right)
$$

has rank equal to $n$. As a consequence

$$
\operatorname{span}\left\{\left[X_{j}, X_{i}\right] \mid i, j=1, \ldots, m\right\}=\operatorname{span}\left\{\partial_{t_{1}}, \ldots, \partial_{t_{n}}\right\}
$$

Therefore,

$$
\begin{aligned}
& \operatorname{rank}\left(\operatorname{Lie}\left\{X_{1}, \ldots, X_{m}\right\}(0,0)\right) \\
& =\operatorname{dim}\left(\operatorname{span}\left\{\partial_{x_{1}}, \ldots, \partial_{x_{m}}, \partial_{t_{1}}, \ldots, \partial_{t_{n}}\right\}\right)=m+n
\end{aligned}
$$

This shows that $\mathbb{G}$ is a Carnot group of step two and generators $X_{1}, \ldots, X_{m}$.
We explicitly remark that the linear independence of the matrices

$$
C^{(1)}, \ldots, C^{(n)}
$$

is also necessary for $\mathbb{G}$ to be a Carnot group. Then, every Carnot group of step two and $m$ generators is of the type described here. Moreover, the above arguments show that there exist Carnot groups of any dimension $m \in \mathbb{N}$ of the first layer and any dimension $n \leq m(m-1) / 2$ of the second layer: it suffices
to choose $n$ linear independent matrices $B^{(1)}, \ldots, B^{(n)}$ in the vector space of the skew-symmetric $m \times m$ matrices (which has dimension $m(m-1) / 2$ ) and define the composition law as in (1.69). Finally, by means of the general results on stratified groups in Section 1.8, we have the following remarkable result.

Theorem 1.5.4. The $N$-dimensional stratified groups of step two and $m$ generators are characterized by being (canonically isomorphic to) $\left(\mathbb{R}^{N}, \circ\right)$ with the Lie group law as in (1.69) where the $B^{(k)}$ 's are $m \times m$ linearly independent skew-symmetric matrices. The group of dilations is given by (1.70).

### 1.5.6 Groups of Heisenberg type

Let $\mathbb{H}=\left(\mathbb{R}^{m+n}, \circ, \delta_{\lambda}\right)$ be the homogeneous Lie group with composition law (1.69) and the group of dilations as in (1.70). Let us also assume that the matrices $B^{(1)}, \ldots, B^{(n)}$ have the following properties:

1. $B^{(j)}$ is a $m \times m$ skew-symmetric and orthogonal matrix, for every $j \leq n$;
2. $B^{(i)} B^{(j)}=-B^{(j)} B^{(i)}$, for every $i, j \in\{1, \ldots, n\}$ with $i \neq j$.

If all these conditions are satisfied, $\mathbb{G}$ is called a group of Heisenberg-type, in short, a H-type group.

An H-type group is a Carnot group, since conditions (1) and (2) imply the linear independence of $B^{(1)}, \ldots, B^{(n)}$. Indeed, if $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right) \in \mathbb{R}^{N} \backslash\{0\}$ then $\frac{1}{|\alpha|} \sum_{s=1}^{n} \alpha_{s} B^{(s)}$ is orthogonal (hence non-vanishing) as the following computation shows:

$$
\begin{aligned}
& \left(\frac{1}{|\alpha|} \sum_{s=1}^{n} \alpha_{s} B^{(s)}\right) \cdot\left(\frac{1}{|\alpha|} \sum_{s=1}^{n} \alpha_{s} B^{(s)}\right)^{T}=-\frac{1}{|\alpha|^{2}} \sum_{r, s \leq n} \alpha_{r} \alpha_{s} B^{(r)} B^{(s)} \\
& =-\frac{1}{|\alpha|^{2}} \sum_{r \leq n} \alpha_{r}^{2}\left(B^{(r)}\right)^{2}-\frac{1}{|\alpha|^{2}} \sum_{r, s \leq n, r \neq s} \alpha_{r} \alpha_{s} B^{(r)} B^{(s)}=\mathbb{I}_{m}
\end{aligned}
$$

Here we used the following facts: $\left(B^{(r)}\right)^{2}=-\mathbb{I}_{m}$ since $B^{(r)}$ is skew-symmetric and orthogonal; $B^{(r)} B^{(s)}=-B^{(s)} B^{(r)}$ from condition (2) above.

The generators of $\mathbb{G}$ are the vector fields (see (1.71))

$$
X_{i}=\partial x_{i}+\frac{1}{2} \sum_{k=1}^{n}\left(\sum_{l=1}^{m} b_{i, l}^{(k)} x_{l}\right) \partial t_{k}, \quad i=1, \ldots, m
$$

A direct computation shows that the canonical sub-Laplacian $\Delta_{\mathbb{G}}=\sum_{i=1}^{m} X_{i}^{2}$ can be written as follows

$$
\begin{aligned}
\Delta_{\mathbb{G}}= & \Delta_{x}+\frac{1}{4} \sum_{h, k=1}^{n}\left\langle B^{(h)} x, B^{(k)} x\right\rangle \partial_{t_{h} t_{k}} \\
& +\sum_{k=1}^{m}\left\langle B^{(k)} x, \nabla_{x}\right\rangle \partial_{t_{k}}+\sum_{k=1}^{n} \operatorname{trace}\left(B^{(k)}\right) \partial_{t_{k}}
\end{aligned}
$$

On the other hand, by conditions (1) and (2), $\left\langle B^{(h)} x, B^{(h)} x\right\rangle=|x|^{2}$ while, for $h \neq k,\left\langle B^{(h)} x, B^{(k)} x\right\rangle=0$ since $\left\langle B^{(h)} x, B^{(k)} x\right\rangle=-\left\langle B^{(k)} B^{(h)} x, x\right\rangle=$ $\left\langle B^{(h)} B^{(k)} x, x\right\rangle=-\left\langle B^{(k)} x, B^{(h)} x\right\rangle$. We also have trace $\left(B^{(k)}\right)=0$ since $B^{(k)}$ is skew-symmetric. Then $\Delta_{\mathbb{G}}$ takes the form

$$
\begin{equation*}
\Delta_{\mathbb{G}}=\Delta_{x}+\frac{1}{4}|x|^{2} \Delta_{t}+\sum_{k=1}^{n}\left\langle B^{(k)} x, \nabla_{x}\right\rangle \partial_{t_{k}} \tag{1.72}
\end{equation*}
$$

Remark 1.5.5. The first layer of a group of Heisenberg type has even dimension $m$. Indeed, if $B$ is a $m \times m$ skew-symmetric orthogonal matrix, we have $\mathbb{I}_{m}=$ $B B^{T}=-B^{2}$, whence $1=(-1)^{m}(\operatorname{det} B)^{2}$.
Remark 1.5.6. With the previous notation, if $\mathbb{H}=\left(\mathbb{R}^{m+n}, \circ, \delta_{\lambda}\right)$ is a $H$-type group, then $\mathfrak{z}=\left\{(0, t) \mid t \in \mathbb{R}^{n}\right\}$ is the center of $\mathbb{H}$. Indeed, let $(y, t) \in \mathbb{H}$ be such that $(x, s) \circ(y, t)=(y, t) \circ(x, s)$ for every $(x, s) \in \mathbb{H}$. This holds iff $\left\langle B^{(k)} x, y\right\rangle=\left\langle B^{(k)} y, x\right\rangle$ for any $x \in \mathbb{R}^{m}$ and any $k \in\{1, \ldots, n\}$. Then, since $\left(B^{(k)}\right)^{T}=-B^{(k)}$,

$$
\left\langle B^{(k)} y, x\right\rangle=0, \quad \forall x \in \mathbb{R}^{m}, \quad \forall k \in\{1, \ldots, n\}
$$

so that $y=0$ because $B^{(k)}$ is orthogonal, hence non-singular.
Remark 1.5.7. The classical Heisenberg group on $\mathbb{R}^{2 k+1}$ is a H-type group. It corresponds to the case $m=2 k, n=1$ and

$$
B^{(1)}=\operatorname{diag}\left\{\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right), \ldots,\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right)\right\}, \quad \text { the block occurring } k \text { times. }
$$

The classical Heisenberg groups are the only (up to isomorphism) H-type groups with one-dimensional center.

Remark 1.5.8. Groups of Heisenberg type with center of dimension $n \geq 2$ do exist. For example, the following two matrices

$$
B^{(1)}=\left(\begin{array}{cccc}
0 & -1 & 0 & 0 \\
1 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 \\
0 & 0 & 1 & 0
\end{array}\right), B^{(2)}=\left(\begin{array}{cccc}
0 & 0 & 1 & 0 \\
0 & 0 & 0 & -1 \\
-1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0
\end{array}\right)
$$

satisfy conditions (1)-(2) and hence they define in $\mathbb{R}^{6}=\mathbb{R}^{4} \times \mathbb{R}^{2}$ a H-type group whose center has dimension 2. The above matrices $B^{(1)}$ and $B^{(2)}$ together with

$$
B^{(3)}=\left(\begin{array}{cccc}
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0 \\
0 & -1 & 0 & 0 \\
-1 & 0 & 0 & 0
\end{array}\right)
$$

define in $\mathbb{R}^{7}=\mathbb{R}^{4} \times \mathbb{R}^{3}$ a H-type group whose center has dimension 3 .
Remark 1.5.9. The following result holds (see [30, Corollary 1]). Let m, $n$ be two positive integers. Then there exists a H-type group of dimension $m+n$ whose center has dimension $n$ if and only if it holds $n<\rho(m)$, where $\rho$ is the so-called Hurwitz-Radon function, i.e.,

$$
\rho: \mathbb{N} \rightarrow \mathbb{N}, \quad \rho(m):=8 p+q, \quad \text { ove } \quad m=(\text { odd }) \cdot 2^{4 p+q}, 0 \leq q \leq 3
$$

We explicitly remark that if $m$ is odd, then $\rho(m)=0$, whence the first layer of any H-type group has even dimension (as we already proved in Remark 1.5.5).

Remark 1.5.10. The groups of Heisenberg-type were introduced by A. Kaplan in [30]. Kaplan's definition of H-type groups is more abstract than the one given here. We shall show that, up to an isomorphism, the two definitions are equivalent.

### 1.5.7 Sum of Carnot Groups

Suppose we are given two homogeneous stratified groups $\mathbb{G}^{(1)}=\left(\mathbb{R}^{N}, \circ^{(1)}\right)$, $\mathbb{S}^{(2)}=\left(\mathbb{R}^{M}, \circ^{(2)}\right)$ with dilations

$$
\begin{array}{ll}
\delta_{\lambda}^{(1)}(x)=\left(\lambda x^{(1)}, \ldots, \lambda^{r} x^{(r)}\right), & x \in \mathbb{G}^{(1)} \\
\delta_{\lambda}^{(2)}(y)=\left(\lambda y^{(1)}, \ldots, \lambda^{s} y^{(s)}\right), & y \in \mathbb{G}^{(2)}
\end{array}
$$

where $x^{(i)} \in \mathbb{R}^{N_{i}}, i \leq r, N_{1}+\cdots+N_{r}=N$ and $y^{(i)} \in \mathbb{R}^{M_{i}}, i \leq s, M_{1}+\cdots+$ $M_{s}=M$. Let $\Delta_{\mathbb{G}^{(1)}}=\sum_{j=1}^{N_{1}} X_{j}^{2}$ and $\Delta_{\mathbb{G}^{(2)}}=\sum_{j=1}^{M_{1}} Y_{j}^{2}$ be the canonical subLaplacians on $\mathbb{G}^{(1)}$ and $\mathbb{G}^{(2)}$, respectively. We define a homogeneous stratified group $\mathbb{G}$ on $\mathbb{R}^{N+M}$ as follows. Suppose $r \leq s$. If $(x, y) \in \mathbb{R}^{N} \times \mathbb{R}^{M}$, we consider the following permutation of the coordinates

$$
R(x, y)=\left(x^{(1)}, y^{(1)}, \ldots, x^{(r)}, y^{(r)}, y^{(r+1)}, \ldots, y^{(s)}\right)
$$

We then denote the point of $\mathbb{G} \equiv \mathbb{R}^{N+M}$ by $z=R(x, y)$. We finally define the group law o and the dilations $\delta_{\lambda}$ on $\mathbb{G}$ as one can expect: for every $z=$ $R(x, y), \zeta=R(\xi, \eta) \in \mathbb{G}$, we set

$$
z \circ \zeta=R\left(x \circ{ }^{(1)} \xi, y \circ{ }^{(2)} \eta\right), \quad \delta_{\lambda} z=R\left(\delta_{\lambda}^{(1)} x, \delta_{\lambda}^{(2)} y\right)
$$

It is then easily checked that $\left(\mathbb{G}, \circ, \delta_{\lambda}\right)$ is a homogeneous stratified group of step $s$ and $N_{1}+M_{1}$ generators. Moreover, the canonical sub-Laplacian on $\mathbb{G}$ is the sum of the sub-Laplacians on $\mathbb{G}^{(1)}$ and $\mathbb{G}^{(2)}$ :

$$
\Delta_{\mathbb{G}}=\Delta_{\mathbb{G}^{(1)}}+\Delta_{\mathbb{G}^{(2)}}=\sum_{j=1}^{N_{1}} X_{j}^{2}+\sum_{j=1}^{M_{1}} Y_{j}^{2}
$$

### 1.5.8 Carnot groups with homogeneous dimension $Q \leq 3$

Let $\mathbb{G}=\left(\mathbb{R}^{N}, \circ, \delta_{\lambda}\right)$ be a Carnot group with homogeneous dimension $Q \leq 3$. We recall that $Q=\sum_{j=1}^{r} j N_{j}$, where $r$ and $N_{1}, \ldots, N_{r}$ are, respectively, the step of $\mathbb{G}$ and the dimensions of the layers $\mathfrak{g}_{1}, \ldots, \mathfrak{g}_{r}$ of $\mathbb{G}$. Obviously, the group is not the Euclidean group in $\mathbb{R}^{N}$ iff $\mathfrak{g}_{2} \neq\{0\}$, i.e., $r \geq 2$. In this case, the first layer $\mathfrak{g}_{1}$ must be at least two-dimensional since $\left[\mathfrak{g}_{1}, \mathfrak{g}_{1}\right]=\mathfrak{g}_{2} \neq\{0\}$. This shows that any non-Euclidean Carnot group has homogeneous dimension $Q \geq 4$. Thus, if $Q \leq 3$ then $\mathbb{G}$ is the Euclidean group in $\mathbb{R}^{N}$, i.e., $\circ=+$ and $\delta_{\lambda}(x)=\lambda x$. The sub-Laplacians on $\mathbb{G}$ are the second order elliptic operators with constant coefficients. The canonical sub-Laplacians are $\mathrm{d}^{2} / \mathrm{d} x_{1}^{2}$ in $\mathbb{R}(Q=$ $N=1), \partial_{x_{1}}^{2}+\partial_{x_{2}}^{2}$ in $\mathbb{R}^{2}(Q=N=2)$, and $\partial_{x_{1}}^{2}+\partial_{x_{2}}^{2}+\partial_{x_{3}}^{2}$ in $\mathbb{R}^{3}(Q=N=3)$.

