# Uniqueness for the determination of unknown boundary and impedance with homogeneous Robin condition

Valeria Bacchelli \*

#### Abstract

We consider the problem of determining the corroded portion of the boundary of a n-dimensional body (n=2, 3) and the impedance by two measures on the accessible portion of the boundary. On the unknown boundary part it is assumed the Robin homogeneous condition.

 $2000\ Mathematical\ Subject\ Classification.\ 35R30,\ 35R25,\ 35R3510.$ 

**Key words.** Inverse boundary value problems, corrosion, thermal imaging, unique continuation.

### 1 Introduction

In this paper we deal with a classical inverse problem. Assume  $\Omega$  be a bounded connected domain in  $\mathbb{R}^n$ , whose boundary  $\partial\Omega$  belongs to  $C^{2,\alpha}$  class,  $0 < \alpha < 1$ ; suppose  $\partial\Omega = \overline{\Gamma^a} \cup \overline{\Gamma^i}$ , where  $\Gamma^i$  and  $\Gamma^a$  are two open connected disjoint portions of  $\partial\Omega$ . Assume that  $\Gamma^i$  is unknown and inaccessible (perhaps  $\Gamma^i$  is some interior connected component of  $\partial\Omega$  or some inaccessible portion of the exterior component of  $\partial\Omega$ ), while  $\Gamma^a$  is known and accessible for input and output measurements. Let us consider the solution u of the following mixed boundary value problem

$$\begin{cases} \Delta u = 0, & \text{in } \Omega, \\ \frac{\partial u}{\partial \nu} = g, & \text{on } \Gamma^a, \\ \frac{\partial u}{\partial \nu} + \gamma u = 0, & \text{on } \Gamma^i, \end{cases}$$
(1)

where  $\nu$  is the exterior unit normal to  $\partial\Omega$ , g is an assigned function,  $\gamma \neq 0$ .

Suppose  $g \in C^{1,\alpha}(\Gamma^a)$ ,  $supp \ g \subset \Gamma^a$ ,  $\gamma \in C^{1,\alpha}(\Gamma^i)$ ,  $\gamma \ge 0$ ,  $\gamma \ne 0$ ,  $supp \ \gamma \subset \Gamma^i$ ; it is known [10] that the direct problem (1) has a unique solution  $u \in C^{2,\alpha}(\overline{\Omega})$ .

<sup>\*</sup>Politecnico di Milano, Dipartimento di Matematica "F.Brioschi", Piazza L. da Vinci, 32, 20133 Milano, Italy (valeria.bacchelli@polimi.it). This work is supported by the Italian Project PRIN 2006019280-003

The inverse problem consists in determining  $\Gamma^i$  and  $\gamma$  provided  $u|_{\Sigma}$ ,  $\Sigma \subset \Gamma^a$ , is known.

This problem arises from non-destructive testing in corrosion detection, where  $\Gamma^i$  represents a corroded portion of  $\partial\Omega$  and we will determine  $\Gamma^i$  and the impedance  $\gamma$  by suitable inspections and measurements on the accessible portion  $\Gamma^a$  of the boundary of  $\Omega$ . We consider such an inverse problem also where  $\Omega = \widetilde{\Omega} \setminus D$ ,  $\Omega$  bounded connected,  $D \subset \subset \widetilde{\Omega}$ ,  $\Gamma^i = \partial D$ ,  $\Gamma^a = \partial \widetilde{\Omega}$ : we are interested, by electrostatic measures or thermal imaging techniques, in identifying D and the coefficient  $\gamma$  by measurements on  $\Gamma^a$ , the external and accessible part of  $\partial\Omega$ .

Many authors have treated uniqueness and stability of  $\Gamma^i$  in the case where on  $\Gamma^i$  it is assumed a Neumann or a Dirichlet condition (see, e.g., [1], [3], [12], [13], [14], [16], [19]).

Concerning the Robin condition, we recall that in [11], assuming  $\Omega$  a thin rectangular plate, local uniqueness of  $\Gamma^i$  is proved. In [18] two different algorithms are presented in order to reconstruct  $\Gamma^i$ . Regarding the impedance  $\gamma$ , in [8] it is introduced a numerical algorithm for recovering such a coefficient. Moreover we recall that different stability estimates for  $\gamma$  have been proved: in [5] a monotone Lipschitz stability estimate, in [6] a local Lipschitz stability estimate, in [2] a log-type stability estimate.

In [4] it is proved, by counterexamples, that a single measurement  $(g, u|_{\Sigma})$  is not sufficient to determine simultaneously the shape  $\Gamma^i$  and the impedance  $\gamma$  and the same holds if, fixed  $\gamma$  a known constant, the only aim is to determine  $\Gamma^i$ .

In the present paper we are able to show that two Cauchy data pairs, that is  $(g, u|_{\Sigma})$ ,  $(\tilde{g}, \tilde{u}|_{\Sigma})$ , guarantee simultaneously uniqueness of  $\Gamma^i$  and  $\gamma$ , provided  $g, \tilde{g}$  are linearly independent and one of them, say g, is positive.

### 2 The uniqueness theorem

**Theorem 1** Let  $\Omega_j$ , j = 1, 2, be a bounded connected domain in  $\mathbb{R}^n$ , whose boundary  $\partial \Omega_j$  is of  $C^{2,\alpha}$  class,  $0 < \alpha < 1$ . Let us assume that  $\partial \Omega_j = \overline{\Gamma^a} \cup \overline{\Gamma_j^i}$ , j = 1, 2, where  $\Gamma^a$ ,  $\Gamma_j^i$  are two open connected disjoint sets. Suppose  $\gamma_j \in C^{1,\alpha}(\Gamma_j^i)$ , j = 1, 2,  $\gamma_j \ge 0$ ,  $\gamma_j \not\equiv 0$ ,  $supp \ \gamma_j \subset \Gamma_j^i$ . Let be assigned two non trivial functions  $g, \ \tilde{g} \in C^{1,\alpha}(\Gamma^a)$ ,  $supp \ g, \ supp \ \tilde{g} \subset \Gamma^a$ ;  $suppose \ g, \ \tilde{g}$  be linearly independent and  $g \ge 0$ . Let  $u_j, \ j = 1, 2$ , be the solution to (1), where  $\Omega = \Omega_j$ ,  $\gamma = \gamma_j$  and the Neumann datum on  $\Gamma^a$  is g. Let  $\tilde{u}_j, \ j = 1, 2$ , be the solution to (1), where  $\Omega = \Omega_j, \ \gamma = \gamma_j$  and the Neumann datum on  $\Gamma^a$  is  $\tilde{g}$ . Let  $be \ \Sigma \subset \Gamma^a$ ,  $\Sigma$  open in the relative topology of  $\partial \Omega$ .

Then, if

$$u_1|_{\Sigma} = u_2|_{\Sigma}, \quad \widetilde{u}_1|_{\Sigma} = \widetilde{u}_2|_{\Sigma}, \quad (2)$$

we have

$$\Gamma_1^i = \Gamma_2^i, \quad \gamma_1 = \gamma_2. \tag{3}$$

**Proof.** The regularity assumptions on  $\Omega_j$ ,  $\gamma_j$ , j = 1, 2, g,  $\tilde{g}$  garantee [10] that  $u_j$ ,  $\tilde{u}_j \in C^{2,\alpha}(\overline{\Omega_j})$ , j = 1, 2. We observe moreover that  $u_j$  is positive on  $\overline{\Omega_j}$ , j = 1, 2; on the contrary, if there exists a point P in  $\overline{\Omega_j}$  such that  $u_j(P) \leq 0$ , by the maximum principle [17], denoting  $Q \in \partial \Omega_j$  the minimum point of  $u_j$  in  $\overline{\Omega_j}$ , also  $u_j(Q) \leq 0$ . The point Q cannot belong to  $\Gamma^a$ , since this contradicts the Hopf maximum principle [17], being  $g = \frac{\partial u_j}{\partial \nu}(Q) \geq 0$ ; the point Q cannot belong to  $\Gamma_j^i$ , since the condition on  $\Gamma_j^i$  implies  $\frac{\partial u_j}{\partial \nu}(Q) \geq 0$  and that contradicts again the Hopf maximum principle.

We prove first that  $\Gamma_1^i = \Gamma_2^i$ . By contradiction assume for istance that  $\Omega_1 \setminus \Omega_2 \neq \emptyset$ . Denote by G the connected component of  $\Omega_1 \cap \Omega_2$  such that  $\Sigma \subset \overline{G}$ . Since

$$u_1|_{\Sigma} = u_2|_{\Sigma}, \quad \widetilde{u}_1|_{\Sigma} = \widetilde{u}_2|_{\Sigma}, \quad (4)$$

and

$$\frac{\partial u_1}{\partial \nu}|_{\Sigma} = \frac{\partial u_2}{\partial \nu}|_{\Sigma} , \quad \frac{\partial \widetilde{u}_1}{\partial \nu}|_{\Sigma} = \frac{\partial \widetilde{u}_2}{\partial \nu}|_{\Sigma} , \qquad (5)$$

Holmgren's theorem implies  $u_1 \equiv u_2$ ,  $\widetilde{u_1} \equiv \widetilde{u_2}$  in a small ball and then, by unique continuation property, we get that  $u_1 \equiv u_2$  in G and  $\widetilde{u_1} \equiv \widetilde{u_2}$  in G. Let us consider  $\Omega_1 \setminus G$  and denote with N the exterior unit normal to  $\partial(\Omega_1 \setminus G)$ . Then  $u_1$  satisfies the problem

$$\begin{cases} \Delta u_1 = 0, & \text{in } \Omega_1 \backslash G, \\ \frac{\partial u_1}{\partial N} + \gamma_1 u_1 = 0, & \text{on } \partial(\Omega_1 \backslash G) \cap \Gamma_1^i, \\ -\frac{\partial u_1}{\partial N} + \gamma_2 u_1 = 0, & \text{on } \partial(\Omega_1 \backslash G) \cap \Gamma_2^i, \end{cases}$$

that is  $u_1$  satisfies on  $\partial(\Omega_1 \setminus G) \cap \Gamma_1^i$  a Robin condition with coefficient  $\gamma_1$ , while on  $\partial(\Omega_1 \setminus G) \cap \Gamma_2^i$  a Steklov condition with coefficient  $\gamma_2$ . The same is true for  $\widetilde{u_1}$ . As  $u_1 > 0$ , the function  $\lambda = \frac{\widetilde{u_1}}{u_1}$  is regular in  $\overline{\Omega_1 \setminus G}$ .

Since  $\partial(\Omega_1 \setminus G) \subset \partial\Omega_1 \cup \partial\Omega_2$ , we have  $\mathcal{H}^{n-1}(\partial(\Omega_1 \setminus G)) < +\infty$  ( $\mathcal{H}^{n-1}$ denotes the n-1 Hausdorff measure), so we get that [7]  $\Omega_1 \setminus G$  is a set of finite perimeter. Therefore, also by the regularity properties of  $u_1$ ,  $\widetilde{u_1}$ , we are able to apply in  $\Omega_1 \setminus G$  the Gauss-Green formula (see for istance [9], [7]); more precisely we make use of the following equality (see [15]), that is an easy consequence of the Gauss-Green formula

$$\begin{aligned} \int_{\Omega_1 \setminus G} \lambda \left( u_1 \triangle \widetilde{u_1} - \widetilde{u_1} \triangle u_1 \right) + \int_{\Omega_1 \setminus G} u_1^2 \ |\nabla \lambda|^2 \\ &= \int_{\partial^* (\Omega_1 \setminus G)} \lambda \left( u_1 \frac{\partial \widetilde{u_1}}{\partial N} - \widetilde{u_1} \frac{\partial u_1}{\partial N} \right), \end{aligned}$$
(6)

where  $\partial^*(\Omega_1 \setminus G)$  is the reducing boundary in the De Giorgi sense. Since on  $\partial(\Omega_1 \setminus G) \cap \Gamma_1^i$  we have  $u_1 \frac{\partial \widetilde{u}_1}{\partial N} - \widetilde{u_1} \frac{\partial u_1}{\partial N} = u_1(-\gamma_1 \widetilde{u_1}) - \widetilde{u_1}(-\gamma_1 u_1) = 0$ , while on  $\partial(\Omega_1 \setminus G) \cap \Gamma_2^i$ , we have  $u_1 \frac{\partial \widetilde{u}_1}{\partial N} - \widetilde{u_1} \frac{\partial u_1}{\partial N} = u_1(\gamma_2 \widetilde{u_1}) - \widetilde{u_1}(\gamma_2 u_1) = 0$ , than by (6) we get  $\lambda = const$ , so that there exist  $\alpha, \beta \in \mathbb{R}, (\alpha, \beta) \neq (0, 0)$ , such that  $\alpha u_1 + \beta \widetilde{u_1} \equiv 0$  in  $\Omega_1 \setminus G$ . Again by unique continuation property we have  $\alpha g + \beta \widetilde{g} \equiv 0$ , that contradicts the assumption that  $g, \widetilde{g}$  are linearly independent.

Now we prove that  $\gamma_1 = \gamma_2$ . Since  $u_1 \equiv u_2$  in  $\Omega_1$ , we get on  $\Gamma^i$ 

$$\frac{\partial u_1}{\partial \nu} + \gamma_1 u_1 = 0, \ \frac{\partial u_1}{\partial \nu} + \gamma_2 u_1 = 0.$$

Subtracting one to the other, we obtain  $(\gamma_1 - \gamma_2)u_1 = 0$  on  $\Gamma^i$ ; if, by contradiction, there exists  $P \in \Gamma^i$  such that  $(\gamma_1 - \gamma_2)(P) \neq 0$ , we get, as  $\gamma_1 - \gamma_2 \in C^{1,\alpha}(\Gamma^i)$ ,  $(\gamma_1 - \gamma_2) \neq 0$  in  $U(P) \cap \Gamma^i$ , that implies  $u_1 = 0$  in  $U(P) \cap \Gamma^i$  and, at the same time,  $\frac{\partial u_1}{\partial \nu} = 0$  in  $U(P) \cap \Gamma^i$ . This contradicts the assumption  $g \neq 0$ .

**Remark 2** We will remark that the uniqueness result of theorem 1 holds, without any change, also in the case, already presented in the introduction, where  $\Omega$ is a bounded connected domain such that  $\Omega = \widetilde{\Omega} \setminus D$ ,  $D \subset \subset \widetilde{\Omega}$ , and  $\Gamma^i = \partial D$ ,  $\Gamma^a = \partial \widetilde{\Omega}$ .

Remark 3 Instead of problem (1), we can consider the following

$$\begin{cases} \Delta u = 0, & \text{in } \Omega, \\ u = f & \text{on } \Gamma^a, \\ \frac{\partial u}{\partial \nu} + \gamma u = 0, & \text{on } \Gamma^i, \end{cases}$$
(7)

with f assigned,  $f \in C^{2,\alpha}(\Gamma^a)$ ,  $\gamma \in C^{1,\alpha}(\Gamma^i)$ ,  $\gamma \ge 0$ ,  $\gamma \ne 0$ . In such a case the inverse problem consists in determining  $\Gamma^i$  and  $\gamma$  by the knowledge of  $\frac{\partial u}{\partial \nu}|_{\Sigma}$ ,  $\Sigma \subset \Gamma^a$ , being u the solution to (7). Also in this case it is possible to state a theorem analogous to the previous one, that is one can determine  $\Gamma^i$  and  $\gamma$  with two pairs of measurements  $(f, \frac{\partial u}{\partial \nu}|_{\Sigma}), (\tilde{f}, \frac{\partial \tilde{u}}{\partial \nu}|_{\Sigma})$ , provided  $f, \tilde{f}$  are linearly independent and one of them, say f, is positive.

**Remark 4** The result of theorem 1 can be easily extended to the case in which we consider, instead of problem (1), the following

$$\begin{cases} div(A \nabla u) = 0, & \text{in } \Omega, \\ \frac{\partial u}{\partial \nu} = g, & \text{on } \Gamma^a, \\ A \nabla u \cdot \nu + \gamma u = 0, & \text{on } \Gamma^i , \end{cases}$$
(8)

where  $A = \{a_{ij}\}, i, j = 1, ..., n$ , is a symmetric matrix satisfying the uniform ellipticity condition, with  $a_{ij} \in C^{1,\alpha}(\overline{\Omega}), g$  is a non trivial assigned function and  $\gamma \geq 0, \gamma \neq 0$ .

## References

- G. Alessandrini and L. Rondi, Optimal stability for the inverse problem of multiple cavities, J. Diff. Equations 176 (2001), 356-386.
- [2] G. Alessandrini, L. Del Piero and L. Rondi, Stable determination of corrosion by a single electrostatic boundary measurement, Inverse Problems 19 (2003), 973-984.
- [3] E. Beretta and S. Vessella, Stable determination of boundaries from Cauchy data, SIAM J. Math Anal. 30 (1999), 220-235.
- [4] F. Cakoni and R. Kress, Integral equations for inverse problems in corrosion detection from partial Cauchy data, Inverse Problems and Imaging 1 (2007), 229-245.
- [5] S. Chabane and M. Jaoua, Identification of Robin coefficients by means of boundary measurements, Inverse Problems 15 (1999), 1425-1438.
- [6] M. Choulli, Stability estimate for an inverse elliptic problem, J. Inv. Ill-Posed problems 10 (2002), 601-610.
- [7] L.C. Evans and R. F. Gariepy, Measure Theory and Fine Properties of Functions, CRC Press, Boca Raton Ann Arbor London, 1992.
- [8] D. Fasino and G. Inglese, An inverse Robin problem for Laplace's equation: theoretical results and numerical methods, Inverse Problems 15 (1999), 41-48.
- [9] H. Federer, Geometric Measure Theory, Springer-Verlag, Berlin Heidelberg New York, 1969R.
- [10] D. Gilbarg and N. S. Trudinger, Elliptic Partial Differential Equations of Elliptic Type, Springer-Verlag, 1983.
- [11] G. Inglese and F. Mariani, Corrosion detection in conducting boundaries, Inverse Problems 20 (2004), 1207-1215.
- [12] P. Kaup and F. Santosa, Nondestructive evaluation of corrosion damage using electrostatic measurements, J. Nondestruct. Eval. 14 (1995), 127-136.
- [13] R. Kress, Inverse Dirichlet problem and conformal mapping, Math. Comput. Simul. 6 (2004), 255-265.
- [14] R. Kress and W. Rundell, Non linear integral equations and the iterative solution for an inverse boundary value problem, Inverse Problems 21 (2005), 1207-1223.
- [15] M. H. Martin, Linear and non linear boundary problems for harmonic functions, Proceedings of the American Mathematical Society 10 (1958), 258-266.

- [16] A. Morassi and E. Rosset, Stable determination of cavities in elastic bodies, Inverse Problems 20 (2004), 453-480.
- [17] M. H. Protter and H. F. Weinberger, Maximum Principles in Differential Equations, Springer-Verlag, New York, 1984.
- [18] W. Rundell, Recovering an obstacle and its impedance from Cauchy data, Inverse problems 24 (2008), 1-22.
- [19] S. Vessella, Quantitative estimates of unique continuation for parabolic equations, determination of unknown time-varying boundaries and optimal stability estimates, Inverse Problems 24 (2008), 1-81.